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environmental monitoring solutions

Aurora 4000

Polar Nephelometer

User Manual

Version: 1.0

www.ecotech.com

Manufacturers statement

Thank you for selecting the Aurora 4000 polar nephelometer.

The Aurora 4000 is the next generation of nephelometers incorporating integrated nephelometry (3 wavelengths 450nm, 525nm, 635nm) with a backscatter shutter that includes angle control. These features allow for a greater range of light scattering measurements beyond what simple backscatter can give. The Aurora 4000 is a product of exceptional quality capable of producing years of maintenance free operation.

This User Manual provides a complete product description including operating instructions, calibration, and maintenance requirements for particulate sampling techniques.

Reference should also be made to the relevant standards, which should be used in conjunction with this manual. Some relevant standards are listed in the References section of this manual.

If, after reading this manual you have any questions or you are still unsure or unclear on any part of the Aurora 4000 then please do not hesitate to contact Ecotech.

Ecotech also welcomes any improvements that you feel would make this a more useable and helpful product then please send your suggestions to us here at Ecotech.



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Notice

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The Aurora lightsource is covered by the following patent:
U.S. Patent Office 7, 671, 988

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Safety requirements

- To reduce the risk of personal injury caused by electrical shock, follow all safety notices and warnings in this documentation.
- If the equipment is used for purposes not specified by Ecotech, the protection provided by this equipment may be impaired.
- Replacement of any part should only be carried out by qualified personnel, only using parts specified by Ecotech. Always disconnect power source before removing or replacing any components.

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3. The model number or a description of each item
4. The serial number of each item, if applicable
5. A description of the problem or the reason you are returning the equipment (eg, sales return, warranty return, etc)

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1. Inspect all instruments thoroughly on receipt. Check materials in the container(s) against the enclosed packing list. If the contents are damaged and/or the instrument fails to operate properly, notify the carrier and Ecotech immediately.
2. The following documents are necessary to support claims:
 - a. Original freight bill and bill lading
 - b. Original invoice or photocopy of original invoice
 - c. Copy of packing list
 - d. Photographs of damaged equipment and container

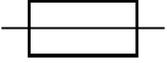
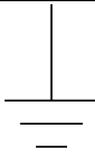
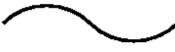
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	Electrical fuse	IEC 60417, No. 5016
	Earth (ground) terminal	IEC 417, No. 5017
	Equipotentiality	IEC 417, No. 5021
	Alternating current	IEC 417, No. 5032
	Caution, hot surface	IEC 417, No. 5041
	Caution, refer to accompanying documents	ISO 3864, No. B.3.1
	Caution, risk of electric shock	ISO 3864, No. B.3.6

Manual Revision History

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1 Introduction

1.1 Description

The Aurora will measure, continuously and in real-time, light scattering in a sample of ambient air due to the presence of particulate matter (specifically, the scattering coefficient σ_{sp}) at three wavelengths (450 Blue, 525 Green and 635 Red).

The polar nephelometer is unique in that it has a backscatter shutter that can be set to any angle between 10° through to 90° at up to 17 different positions. When the backscatter shutter is positioned at a specific angle the nephelometer measures the light scattering from that angle, through to 170°. Each measurement cycle also includes a measurement without the backscatter active or a 0° angle measurement.

Example

A scattering angle set to 20° will measure all the scattering from 20° to 170°,

A scattering angle at 30° will measure all the scattering from 30° to 170°,

The difference between these two angles gives the light scattering for the polar segment of 20° - 30°.

Calibrations and zero/span checks are fully automatic, with checks initiated automatically, at user-selectable intervals. There is provision for several types of calibration gases.

A processor-controlled inlet heater can eliminate the effects of relative humidity on scattering behaviour. The heater can be enabled and disabled by the user.

All these options are available from an easy-to-use menu system with 4-line backlit LCD display and keypad mounted on the instrument case.

The Aurora also features low power consumption, very long-lasting and reliable LED's as the light source and has an exceptional signal-to-noise ratio.

1.2 Specifications

1.2.1 Measurement

Range:

- Measurement: <math><0.25 \text{ to } 2000 \text{ Mm}^{-1}</math>
- Total light scattering angle: 9° – 170°
- Selectable angles: up to 17 angles between 10° - 90° (along with a 18th angle 0° which is standard)
- Wavelengths: 450nm, 525nm, 635nm simultaneously

Lower detectable limit:

- <math>< 0.3 \text{ Mm}^{-1}</math> over 60 seconds integration

Sample flow rate:

- 5 l/minute approx

1.2.2 Calibration

Calibration gases supported:

CO ₂	SF ₆
FM-200	R-12
R 22	R-134

Automatic Calibration intervals:

3, 6, 12, 24 hours, weekly or user designated day

Automatic Calibration types:

Zero Check
Span Check
Zero and Span Check
Zero Adjust

1.2.3 Power

Operating voltage:

- 100-250VAC 50 or 60Hz
- 11-14VDC

Power consumption:

- 60VA max

1.2.4 Operating conditions

Ambient Temperature Range:

- 20-45°C

Relative Humidity

- 10-95%

1.2.5 Physical dimensions

Case dimensions:

- LxWxH = 170 x 700 x 215 mm

Weight: 11.2kg

1.2.6 Communication and Data

Comm ports:

- 1 multidrop (RS232)
- 1 Serial port (RS232)

External I/O

- 2 digital inputs
- 1 digital output

Data properties

Instantaneous: 1 min, 5 min, all

Stored properties: All σ_{sp} , Air Temperature, RH, Pressure, Enclosure Temperature, Time,

Capacity:

<i>Time period</i>	<i>5 min</i>	<i>1 min</i>	<i>All</i>
<i>2 angles</i>	34 days	6 days	8 hours
<i>18 angles</i>	6 days	31 hours	14 hours

1.3 Nomenclature

Span: When gas of known Rayleigh factor is passed through instrument and measured as a reference. This measurement is used to correct measure coefficients.

Zero: When air with no particulate matter is passed through instrument and measured as a reference. This measurement is used to ascertain the effect of air (CO₂, CO etc) on scattering coefficient.

Shutter count: The shutter count is the measurement of light shone directly through a dark glass with known transmittance. This measurement is used as a reference for light intensity and PMT measurement.

Dark count: Measures background light scattering when light source is off (< 5000 are considered typical). Used to subtract from measure count to eliminate noise from background interference.

Measure count: Raw measurement of the light scattering of particulates in the sample air within the cell.

1.4 Background/ Theory

Aerosol and cloud scattering/absorption of light are one of the main influences on solar radiation penetration into the lower parts of the Earth's atmosphere. Nephelometers have predominantly been used to measure light scattering and determine solar radiation entering the Earth's atmosphere

A traditional multi wavelength backscatter nephelometer would allow a researcher to accurately estimate both the total scatter of light by aerosols and how much of this scatter is backscatter (scattered back towards the source).

The Aurora 4000 has been specifically designed with a backscatter shutter that is able to be positioned at any angle between 10 and 90 degrees with up to 18 different angles (including 0°) per measurement cycle.

This more comprehensive look at scattering allows a user to measure the scattering from say 20° to 170° at one measurement angle, then at 30° to 170° at another angle. The user can then determine the specific scattering within the 20° to 30° sector.

The Ecotech Aurora 4000 Polar Nephelometer measures σ_{sp} , the scattering coefficient of light due to particles at three wavelengths 450nm, 525nm, 635nm.

The measurement of σ_{sp} may be used as a measure of aerosol scattering, the higher the value of σ_{sp} the more light scattering that occurs..

The dimension of σ_{sp} are inverse length. The Aurora 4000 reports σ_{sp} in units of the inverse megametre (Mm^{-1}) = $10^{-6} m^{-1}$ (inverse metres).

$1 Mm^{-1} = 10^{-3} km^{-1}$ (inverse kilometres) = $10^{-6} m^{-1}$ (inverse metres).

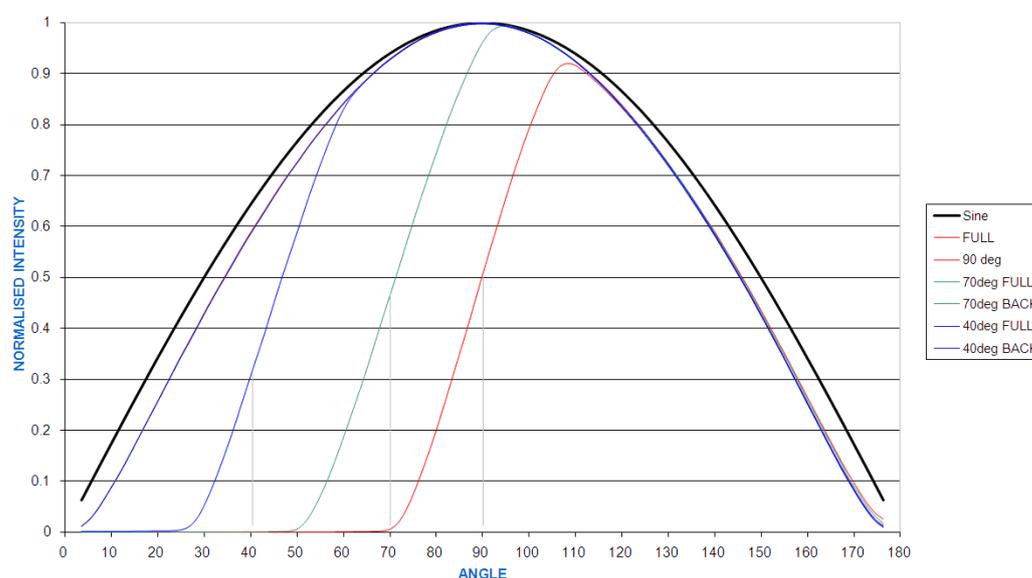


Figure 1 Graphical demonstration of backscatter measurements at 40°, 70° and 90°

1.4.1 Background

Extinction Coefficients σ_{ext}

Attenuation of light (that is, reduction in its intensity) is usually expressed using the **Beer-Lambert law**:

$$I = I_0 e^{-\sigma_{\text{ext}} x}$$

Equation 1 Beer-Lambert law

where:

- I_0 = initial light intensity,
- I = intensity after distance x ,
- x = distance,
- σ_{ext} = the attenuation, or extinction coefficient.

(sometimes the symbol b is used instead of σ_{ext})

The relationship between extinction coefficient and visual range is expressed in **Koschmieder's Formula**.

$$L_v = 3.912 / \sigma_{\text{ext}}$$

Equation 2 Koschmieder's Formula

where:

- L_v = visual range,
- σ_{ext} = extinction coefficient.

The larger σ_{ext} , the more rapidly the light is attenuated (ie reducing visibility).

Assumptions

Light may be attenuated either by scattering off objects or by absorption by objects. Thus the extinction coefficient σ_{ext} may be broken down into a scattering coefficient σ_{scat} and an absorption coefficient σ_{abs} :

$$\sigma_{\text{ext}} = \sigma_{\text{scat}} + \sigma_{\text{abs}}$$

Equation 3 Light attenuation equation

For light attenuation in the atmosphere, the objects responsible can be either gas molecules or airborne particles. The scattering and absorption coefficients may therefore be further broken down into

$$\sigma_{\text{scat}} = \sigma_{\text{sg}} + \sigma_{\text{sp}}$$

Equation 4 Scattering Coefficient

and

$$\sigma_{\text{abs}} = \sigma_{\text{ag}} + \sigma_{\text{ap}}$$

Equation 5 Absorption Coefficient

where the subscripts denote:

- s: scattering
- a: absorption
- g: due to gas molecules
- p: due to particulate matter.

σ_{sp} , for example, is the extinction coefficient due to scattering from particulate matter. Scattering due to gas molecules (coefficient σ_{sg}) is also called 'Rayleigh scattering'.

NO₂ is the most significant gaseous absorber and soot the most significant particulate absorber. However, except in extremely high concentrations, the effects of absorption are negligible compared to the effects of scattering. Therefore, to a very good approximation,

$$\sigma_{\text{ext}} \approx \sigma_{\text{scat}} = \sigma_{\text{sg}} + \sigma_{\text{sp}}.$$

Equation 6 Relationship of Extinction coefficient with scattering Coefficient

It is σ_{scat} that the Ecotech Aurora 4000 measures directly. When the instrument performs a zero adjust in particle-free air (that is, where only Rayleigh scattering is present), the σ_{sg} component of σ_{scat} is subtracted leaving σ_{sp} as the reported parameter.

Higher particulate concentrations mean more scattering, so σ_{sp} is a good measure of particulate pollution.

In urban situations σ_{sp} will be much greater than Rayleigh scattering (σ_{sg}). σ_{sp} is therefore also a good measure of atmospheric visibility.

Effects of Wavelength

Absorption and scattering are dependent on the wavelength of the incident light. The Aurora 4000 uses a light source emitting light at three different wavelengths (infrared to ultra-violet). The three wavelengths (Red 635nm, Green 525nm, Blue 450nm) all produce differential scattering and are affected differently by particles of different size, shape and composition.

- 450nm (blue) interacts strongly with fine and ultrafine particulates (wood fires, automobiles)
- 525nm (green) interacts strongly throughout the human range of visibility (smog, fog, haze)
- 635nm (red) interacts strongly with large particulate matter (pollen, sea salt)

This allows partial characterisation and in-depth analysis of the type of particulates and their effects within the environment. These different wavelengths overlap in measurements and do not directly measure differences in particulate composition.

Effects of Humidity

Above about 60% relative humidity, particles collect water droplets and grow because of the water vapour condensing on them, hence scattering more light.

If enabled (section 1.1.1), the instrument will heat the sample as its humidity approaches that set by the user. This decreases the relative humidity and evaporates the water droplets.

Switching on the heater (dry measurement) would give a more reliable measure of airborne pollutant concentrations, as this evaporates (much of) the water droplets. Switching off the heater (wet measurement) would give a more reliable measure of true scattering of aerosols.

1.4.2 Measurement Theory

During normal operation there are three main measurements being made. They are Dark count, Shutter count and Measure count.

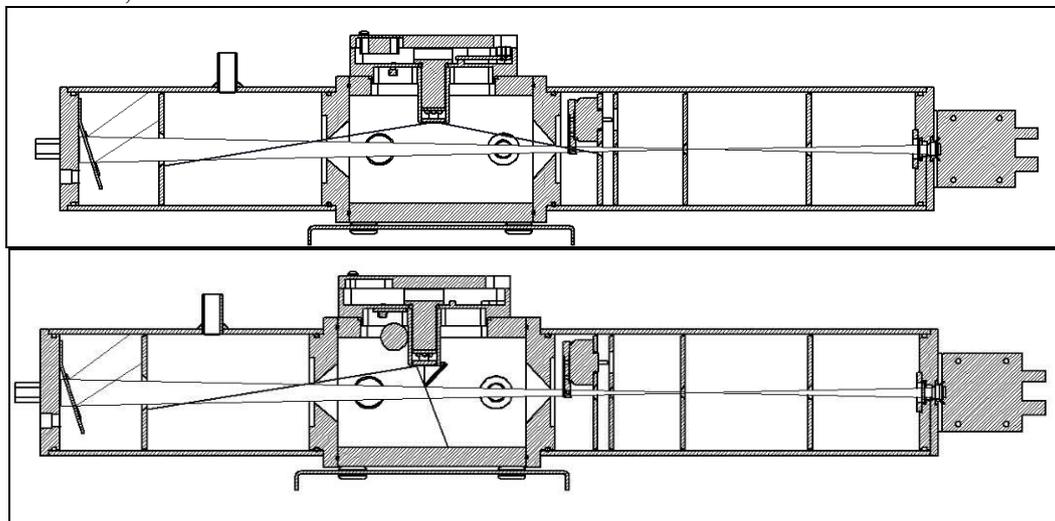


Figure 2 Light path layout, without backscatter (top) and with 90° backscatter (bottom)

Shutter Count

Periodically (every 30 seconds or the next available time after a measurement cycle has finished) the reference shutter mounted inside the cell (see Figure 2), is closed for about 4 seconds. During this time, there is a direct light path from the Light Source, to the shutter and then to the photomultiplier tube. The shutter glass is a material with known transmittance that allows the Aurora to adjust for variations in the measuring system. This measurement does not rely on air scattering. The results from the Shutter measure are stored as the Shutter Count and should be in the order of 0.8M to 1.6M.

Dark Count

The light source periodically flashes on and off in less than 1 second. When the light source is off, the PMT measures the Dark Count. That is, the background light incident upon the PMT when the light source is off. Ideally, this should be 0, however readings up to 5000 are normal, as are small fluctuations.

Measure Count

The measure count is taken when the shutter is open and the light source is on. The measured counts from the PMT are a result of scattering due to gaseous and particulate matter inside the measurement volume. As the concentration of scattering components inside the cell increases, so do the measure counts. Typical measure counts can vary from 5k to 500k. The measure count is measured for each wavelength and the dark count is subtracted.

Measure Ratio

The measure ratio (MR) is the ratio between the Measure count (C_m) and the shutter count (C_{sh}).

$$MR = C_m / C_{sh}$$

Eg. If $C_m = 15,000$ & $C_{sh} = 1,200,000$, then $MR = 12.5 \times 10^{-3}$.

Because the C_{sh} is a stable known source, the MR is directly proportional to σ_{scat} .

If there are changes in the measurement system (ie. Light source intensity or temperature), then both C_m & C_{sh} will change proportionally. Therefore the MR will remain constant. However if the σ_{scat} of the sample changes, then only the C_m will vary.

Measurement sequence

During measurement the light source sequentially emits a short pulse of light (red, green, blue) one at a time. This sequence is repeated for every angle taking approximately 1.5 seconds to complete. This process measures the dark count, measure count and measure ratio are all calculated every second. The shutter count is calculated every 30 sec (or the first available opportunity after a measurement cycle has taken place). These measurements along with stored parameters allow the Aurora to calculate σ_{sp} for every angle at every wavelength.

Kalman Filter

The Aurora 4000 has the option of using a fixed 30 second Moving Average Filter or the advanced digital Kalman filter (selectable from the Report Prefs menu).

The Kalman filter provides the best possible compromise between response time and noise reduction for the type of signal and noise present in the ambient air.

Ecotech's implementation of the Kalman filter enhances the Aurora's measurement method by making the time constant variable, depending on the change rate of the measured value. If the signal rate is changing rapidly, the instrument is allowed to respond quickly. When the signal is steady, a longer integration time is used to reduce noise. The system continuously analyses the signal and uses the appropriate filtering time.

1.4.3 Calibration Theory

During calibration, calibration gas and particle free air are passed through the cell at different times. Both these components have known values of σ_{sp} and σ_{sg} (for each wavelength). The Measure ratio for these components is plotted against the known σ_{sp} , and a linear relationship is formed between σ_{sp} and Measure ratio (for each wavelength).

Note: that the effects of dark count and other variations measured through the shutter count, are compensated for in this relationship.

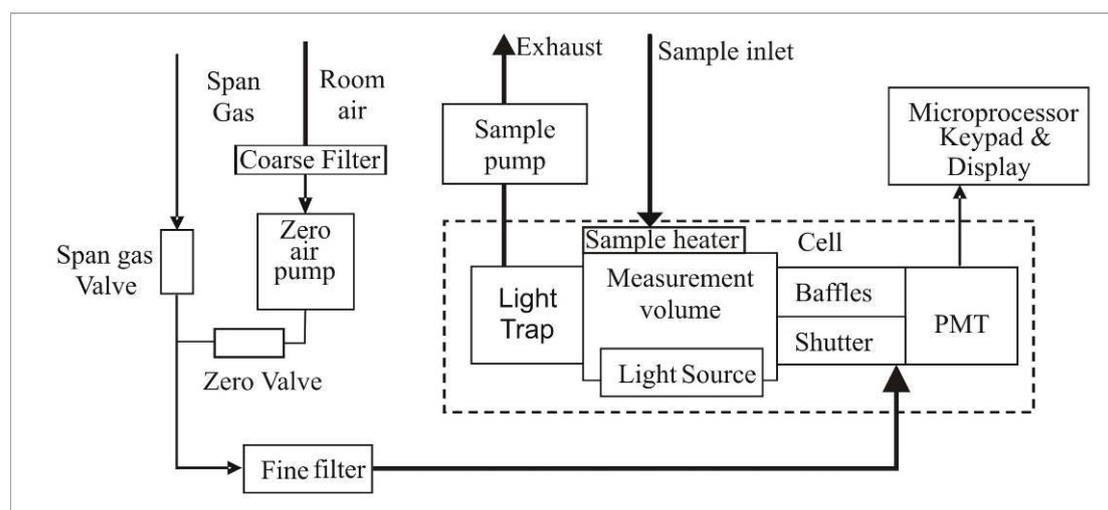


Figure 3 Block Diagram

Zero calibrations are performed with zero air to subtract the Rayleigh scattering component) of σ_{scat} . Span calibrations are performed using certified gas, typically CO₂ or FM-200 gas (HFC-227ea Heptafluoropropane).

Note: Calibrations for all three wavelengths are performed simultaneously

Calibration Example

The following is an example of a typical calibration using CO₂ calibration gas with 525nm (green light source).

During a full calibration two points are measured.

- The span point is measured with CO₂ calibration Gas.
- The Zero point is measured with particle free air.

During the calibration, the Aurora measures the C_m & C_{sh} as well as sample temperature (ST) and barometric pressure (BP). The following results are obtained.

Table 1 Calibration Data

Point	Span	Zero
C_m (Hz)	13692	11582
C_{sh} (Hz)	1,200,000	1,200,000
MR (C_m/C_{sh})	11.41×10^{-3}	9.65×10^{-3}
ST (°K)	300.2	300.2
BP (mBar)	1004	1004
σ_{scat} (10^{-6} m)*	24.79	0

At STP (273.15 °K, 1013.25mBar) and wavelength 525nm:

σ_{scat} for particle free air (Air Rayleigh) = 14.82×10^{-6} m.

σ_{scat} for CO₂ = $2.61 \times 14.82 = 40.19 \times 10^{-6}$ m. (2.61 is the known multiplier of CO₂).

*Use STP normalisation to calculate the σ_{scat} at 300.2°K & 1004mBar as measured in Table 1.

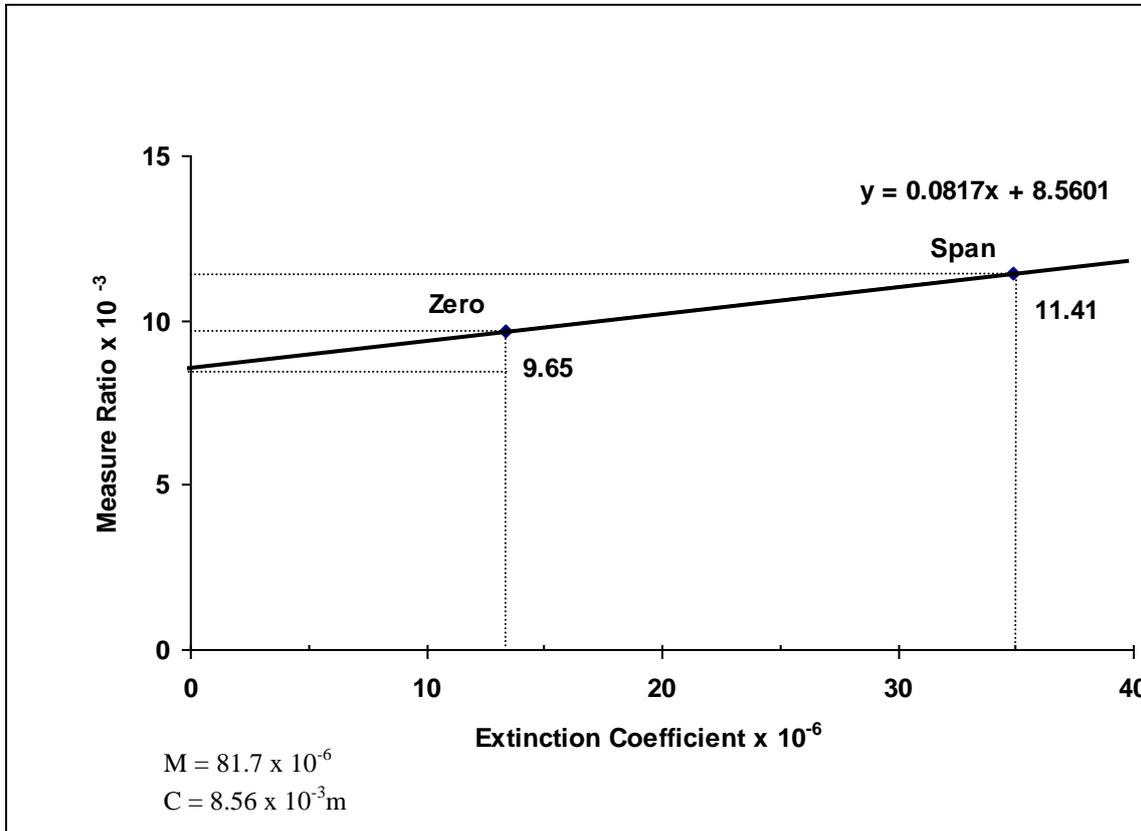


Figure 4 Aurora calibration curve

The values for σ_{scat} and MR are plotted on the above calibration curve. From this curve we can obtain a formula for converting the MR to σ_{scat} .

$$\sigma_{\text{scat}} = (\text{MR} - 8.56) / 0.0817 \text{ (} 10^{-3} \text{)}$$

If for example our MR = 10 then,

$$\sigma_{\text{scat}} = 17.63 \times 10^{-6} \text{ m.}$$

In the Aurora 4000 all results are reported with Air Rayleigh subtracted.

$$\sigma_{\text{sp}} = \sigma_{\text{scat}} - \sigma_{\text{sg}} \text{ where } \sigma_{\text{sg}} = 17.63 - 13.36 = 4.26 \times 10^{-6} \text{ m.}$$

Calibration Stability

When a full calibration is completed, the Aurora 4000 reports a value for Cal Stability. This is an indication of the variation of readings about the mean.

Given 150 samples, let x be the mean and s be the standard error.

$$\text{Cal Stability} = 100 * (1 - 2s/x) .$$

If Cal stability = 95%, then the standard error = 2.5%.

Typically during a calibration of either span or zero, a Cal stability of > 97% should be achieved.

Wall Signal

The Wall signal is the amount of scattering contributed as a result of internal reflections within the cell and foreign matter. The wall signal is calculated after a full calibration. Looking at the graph of Figure 4 the wall signal can be calculated as follows:

$$\text{Wall} = 100 \times (C / MR_{(\text{ZERO})}) = 100 \times (8.56 / 9.65) = 88.7\%.$$

Calibration Gas Constants

Table 2 lists the σ_{sp} for the supported calibration gases at different wavelengths and at STP.

The general formula to calculate the coefficient at a different wavelength:

$$\sigma_{sp}(\lambda_1) = \sigma_{sp}(\lambda_2) \left(\frac{\lambda_2}{\lambda_1} \right)^4$$

So for example:

$$\sigma_{sp}(450) = \sigma_{sp}(520) \left(\frac{520}{450} \right)^4$$

Note: the following table shows the Calibration Gas Constants used by the Aurora during a full calibration. The Aurora readings are with Air Rayleigh subtracted so that for clean particle free air (zero), the Aurora Nephelometer reads 0. All values are at STP.

Table 2 Properties of Calibration Gases at different wavelengths.

Gas Constants							
wavelength	Rayleigh air	CO ₂	fm200	SF6	r12	r22	r134
		2.61	15.3	6.74	15.31	7.53	7.35
450	27.46	71.67	420.14	185.08	420.41	206.77	201.83
525	14.82	38.68	226.75	99.89	226.89	111.59	108.93
635	6.92	18.07	105.95	46.64	105.95	52.14	50.90
Aurora Readings Full Scattering							
wavelength		CO ₂	fm200	SF6	r12	r22	r134
450		44.21	392.68	157.62	392.95	179.31	174.37
525		23.86	211.93	85.07	211.93	96.77	94.11
635		11.15	99.02	39.72	99.02	45.22	43.97

The Aurora 4000 polar nephelometer performs internal calculations when calibrating each angle or measurement. The Aurora 4000 must be calibrated each time the angles being measured are changed, see section 4 for more details.

Wavelength (nm):	525	450	635
Air Rayleigh (10 ⁻⁶ m):	14.82	27.46	6.92
Temp (°K):	273.15	273.15	273.15
Pressure (mBar):	1013.25	1013.25	1013.25

1.5 Instrument description

The Aurora 4000 measures σ_{sp} in the following way:

- Sample air is drawn through the sample inlet into the measurement volume and exits through the sample outlet via the pump.
- The light source illuminates the sample air in the measurement cell
- The light source pulses through the three wavelengths
- This illumination of 3 wavelengths is performed for each angle set within the instrument
- The baffles inside the cell are positioned so that only light scattered inside a narrow cone, at scattering angles between 10° and 170° , reaches the photomultiplier tube and so that multiple scattered light is unlikely to reach the photomultiplier tube.
- The photomultiplier tube produces electrical signals proportional to the intensity of the incident light. Hence the signal produced by the photomultiplier tube is proportional to the scattering coefficient of the sample air, σ_{scat} .
- The light trap and other baffles eliminate unwanted reflections from the light source and scattered light off the non-detecting end of the cell. The cell interior and baffles are coated with a special mat finish black paint to reduce any internal reflections.
- This same procedure is conducted for each wavelength both for full and backscatter. Backscatter involves a backscatter shutter blocking the scatter on the opposite side from the light source, removing forward scatter.

After removing the front cover, you will see the Aurora's components. The following is a brief description of each of these components.

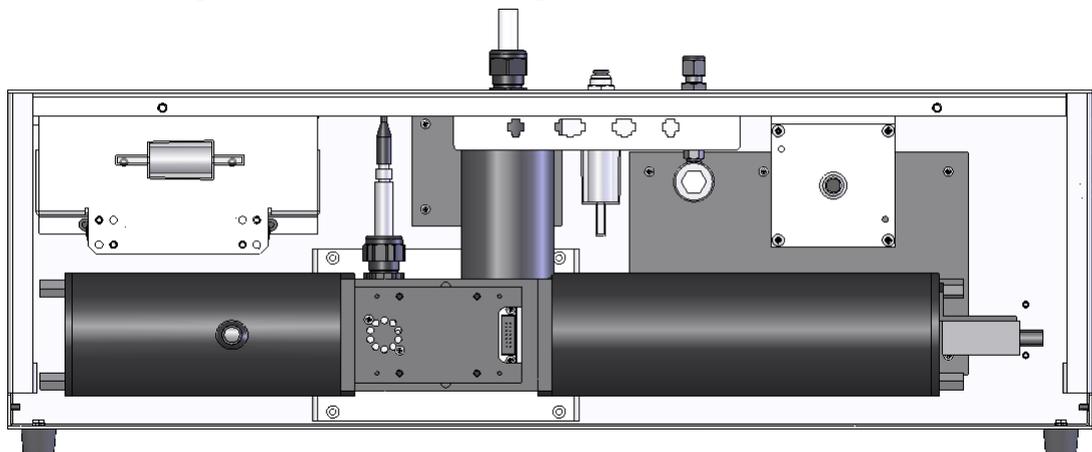


Figure 5 Ecotech Aurora 4000 (with cover removed)

1.5.1 Cell

The cell is the critical part of the Aurora. It is within cell that the optics, the electronics and the pneumatics all come together. The cell pneumatically and optically sealed to prevent stray light and air from entering. It is made of black anodised aluminium with a coating of matt black paint on the inside to reduce internal wall scatter.



Figure 6 Cell

1.5.2 PMT

The PMT (Photo Multiplier Tube) is used to measure the light (photons) resulting from scattering. It is actually a photon counting head and produces an electrical signal (frequency) proportional to the incident light. The output frequency of the PMT ranges from 0 Hz to 1,600,000 Hz. The High voltage supply to operate the PMT is internally generated within the PMT. There is a black rubber cover over the PMT to reduce stray light from increasing the dark counts.



Figure 7 PMT

1.5.3 Reference Shutter

The reference shutter is used to periodically check the operation of the Aurora as well as compensates for any variations in the measuring system. i.e. variations in light source intensity, or wall scatter. The reference shutter composes a solenoid and a piece of glass with known transmittance. It is mounted on a rotary solenoid and is switched in and out of the optical path. Typically when the shutter is switched in it will give a shutter count of around 0.8M-1.6M (though this number can vary depending on PMT sensitivity and light source intensity).



Figure 8 Shutter

1.5.4 Light Source

The light source high powered LEDs (Light Emitting Diodes) of specific wavelengths (Red 635nm, Green 525nm, Blue 450nm). LEDs are used instead of the conventional flash lamps because of much better reliability, stability and lower heating of the sample. Integration can also be performed over a longer period of time because LEDs can be turned on for longer.

The LED array is housed in a black assembly which can be easily removed for cleaning purposes. On the front of the Light Source housing there is a glass diffuser.

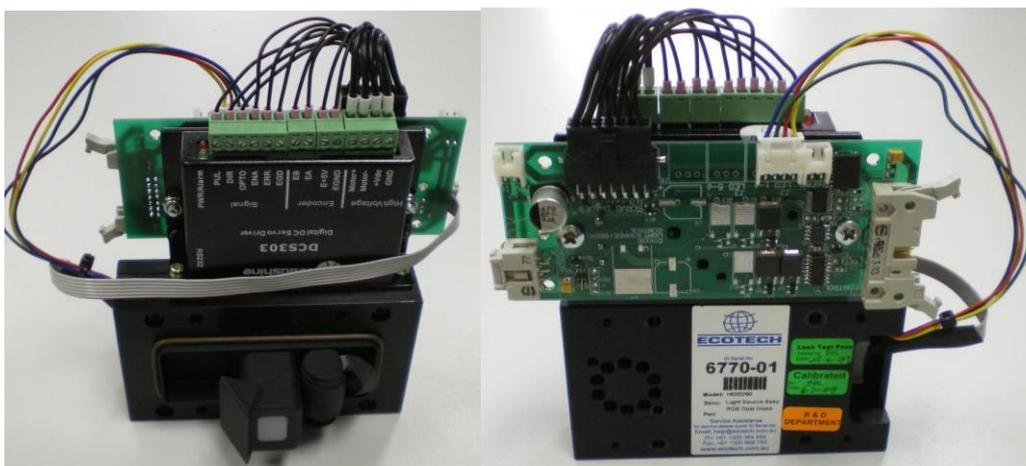


Figure 9 Light source

The opal glass diffuser ensures that the LEDs produce light with a lambertian distribution.

Backscatter

The light source has a backscatter shutter that moves in and out of the light path to any angle between 10° and 90°.

1.5.5 Sample Pump

The sample pump is the means by which large volumes of ambient air is drawn in through the sample inlet, through the cell and out the exhaust. This pump runs continuously except during calibration and start up.



Figure 10 Sample pump

1.5.6 Zero Pump

The Zero air pump is a +12V DC diaphragm pump which draws air through the fine filter providing particle free air (zero calibration or zero check). It is not on during normal measuring mode. The zero pump has a DFU filter on its inlet to protect the pump from dust build up.



Figure 11 Zero pump

1.5.7 Zero Fine Filter

The zero filter works in conjunction with the zero pump to provide the particle free air during zero calibration and zero check. Its filtration efficiency is greater than 99.5% removing particles greater than 0.1 micron in size.



Figure 12 Zero Filter

1.5.8 Span & Zero Valve

The span valve and Zero valve are +12V solenoid valve which are opened during a span calibration/span check or zero calibration respectively. When opened, it allows the calibration gas/zero air to pass into the cell for calibration.



Figure 13 Span and Zero valve

1.5.9 Temperature / RH Sensor

The Temperature and RH sensor are mounted on top of the cell measuring directly in the cell. The temperature and RH sensor are monitored by the microprocessor and their data recorded in the internal data logger.

- The Temperature/RH sensor measures the sample air temperature and is used in the compensation of σ_{sp} for STP (Standard Temperature and Pressure).
- The Temperature/RH sensor measures the Temperature of the sample air. This data is used to control the sample heater, hence controlling the sample temperature up to the desired set point.
- The Temperature/RH sensor measures the RH of the sample air. This data is used to control the sample heater, hence controlling the RH of the sample air down to the desired set point.



Figure 14 Temperature/RH sensor

1.5.10 Pressure Sensor

The air pressure sensor is mounted on the microprocessor board. It is connected pneumatically to the cell to measure the cell pressure. The measured pressure is used to convert the σ_{sp} to Standard Temperature and Pressure. The pressure is also logged internally on the data logger. The pressure sensor also is used to correct calculate the scattering coefficient of the calibration gas due to pressure differences during calibration.



Figure 15 Pressure sensor

1.5.11 Sample Heater

The sample heater (when enabled), controls the body temperature of the cell. The cell temperature sensor is mounted in the cell wall (near the light source). The microprocessor controls the sample heater so that the sample air in the cell is kept at the desired set point for temp or RH.



Figure 16 Cell Heater

- If the Aurora is installed in a room where the sample inlet is taking in outside air and the room temperature is much cooler than the ambient temperature, then the sample heater should be set to the temperature of average ambient temperature (25-30°C).
- If the Aurora is running from batteries (+12v Option) then the sample heater should be disabled (it will reduce battery life significantly).

1.5.12 Microprocessor

The microprocessor board is the heart of the Aurora 4000. It takes the raw count data from the PMT and converts them to real σ_{sp} values. It controls all the pumps, solenoids and light source. It internally logs the data and provides RS232 data and remote control capabilities. It also controls the LCD display and keypad allowing the user to view and modify parameters. The firmware (program) loaded on the microprocessor board is stored in EEPROM and can be upgraded via the serial port. It also contains a real time clock for data logging and auto calibration control. The calibration parameters and user settings are also stored in FLASHROM, so they are not lost during a power failure.



Figure 17 Microprocessor board

1.5.13 Keypad & Display

The Keypad & Display provide the user with an interface so that they can input and retrieve vital operational data. The membrane Keypad comprises of 6 keys for easy access to the menu system. The display comprises of a backlit 4 x 16 character LCD display for displaying data clearly. See section 3.2.1 for more details.



Figure 18 Keypad and Display

1.5.14 Backup Battery

The backup batteries are located next to the microprocessor board. They provide power to the real time clock and logged data when the Aurora 4000 is turned off.

Note if you disconnect the battery while the power is off, the clock settings and all logged data will be lost. However calibration and setup parameters will not be lost. The batteries are two AA 1.5V alkaline cells.

1.5.15 Electrical Connections

The following connections are found on the right side of the instrument (when looking at the screen). The placement of these electrical and communication connections is designed to minimise any interference from liquid spills or dust build up.

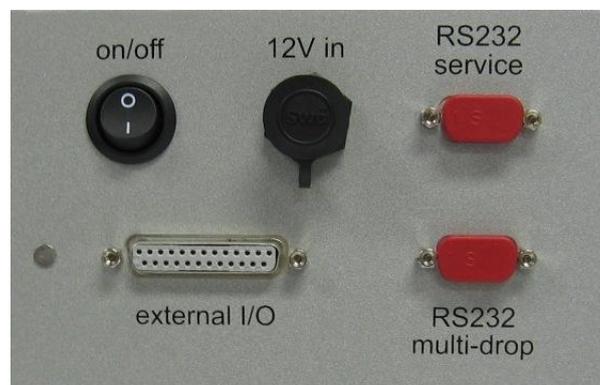


Figure 19 Electrical connections to the Aurora 4000

RS232

There are two RS232 serial ports available on the Aurora 4000, The multi-drop and Service ports. The Multi-drop serial port is used for communication and data download, they can be connected to data logger or in a daisy chain configuration. The service port is used for diagnostic purposes. Refer to section 4.5.1 for further details on setting up the RS232 ports.

12V in

The 12V inlet is where the 12V power pack is connected. This supplies the power for the instrument which will not operate if not plugged in. The Power switch is located on the left side of the connector and must also be turned on (switched down) for the instrument to work.

1.5.16 Pneumatic inlets

The pneumatic inlet connections for the Aurora are located on the top of the instrument case (when looking at screen) so that inlet tubing can be positioned directly above the case and to the external environment (if necessary).



Figure 20 Pneumatic connections to the Aurora 4000

Sample

The ½” port labelled “sample”, is where the sample inlet is connected. During transport or storage, this port should be closed to avoid debris from falling into the cell.

Zero

The Aurora 4000 has its own internal filters for generating particle free air. There is no need for any further connections on the “zero gas” port.

Span

The calibration gas used for calibrating the Aurora is connected here as discussed in section 2.2.1.

Warning: DO NOT leave FM200 gas connected to the Aurora for long periods of time as this may cause condensation and damage to the calibration control kit.

Exhaust

The Exhaust is located at the top of the instrument to the right side of the other pneumatic connections. The exhaust is pumped up through this outlet which has the ability to be vented out with a screw in exhaust hose (optional)

Note: During normal operation make sure that the exhaust is not covered.

2 Installation

The correct installation of the Aurora 4000 is very important to ensure that the instrument operates correctly and gives you reliable data. Please read the following sections carefully.

2.1 Initial check

Packaging

The packaging which the Aurora 4000 is transported in is specifically designed to minimise the effects of shock and vibration during transportation. Ecotech recommends that the packaging be kept if there is a likelihood that the instrument is going to be relocated.

Remove all packaging including red caps from instrument and store in a secure area. In the event that the packaging is to be disposed of, all the materials used are recyclable and should be disposed of accordingly.

Items Received

With the delivery of the Aurora 4000, you should have received the following:

- | | | |
|--------------------------------------|------------|------------------|
| • Ecotech Aurora 4000 instrument | | PN: E010007 |
| • Power cord | | PN: ----- |
| • Serial cable | | PN: C020016 |
| • Manual | | PN:M010038 |
| • Software Utilities CD. | | PN: COM-1018 |
| • Leak test filter | | PN: ZRU-57002758 |
| • Rain cap with insect screen | (optional) | PN: ECO-M9003011 |
| • Inlet tube (0.8m, 1m, 1.5m, or 2m) | (optional) | PN: H02032X* |
| • Wall mounting bracket | (optional) | PN: H020005 |
| • Roof Flange | (optional) | PN: ECO-M9003004 |
| • Calibration Kit | (optional) | PN: H020331 |
| • Service Kit | (optional) | PN: H020335 |
| • Exhaust tube kit | (optional) | PN: H020335 |
| • External Pump Kit | (optional) | PN: H020332 |

* X denotes either 0 (800ml insulated), 2 1m un-insulated), 3 (1.5m un-insulated) or 4 (2m uninsulated) for sample inlet tube.

Please check that all these items have been delivered undamaged. If there is any item damaged or if you are unsure, please contact your supplier BEFORE turning on the instrument.

2.2 Assembly

2.2.1 Connecting the Calibration Gas

- Consult your local regulations for the positioning of the gas cylinder.
- In most cases the gas cylinders should be located outside the building and secured to a solid wall.
- The Calibration gas should be high purity 99.99% gas for accurate calibration.
- The calibration gas cylinder should be fitted with a regulator and flow meter.
- It should also include at least 1 metre coiled metal line to bring gas temperature to room temperature, especially if a refrigerant gas is used.

Ecotech can supply an optional Calibration kit (H020331) which provides all the necessary connections to connect the gas cylinder to the Aurora. The recommended gas delivery system is shown in Figure 21.

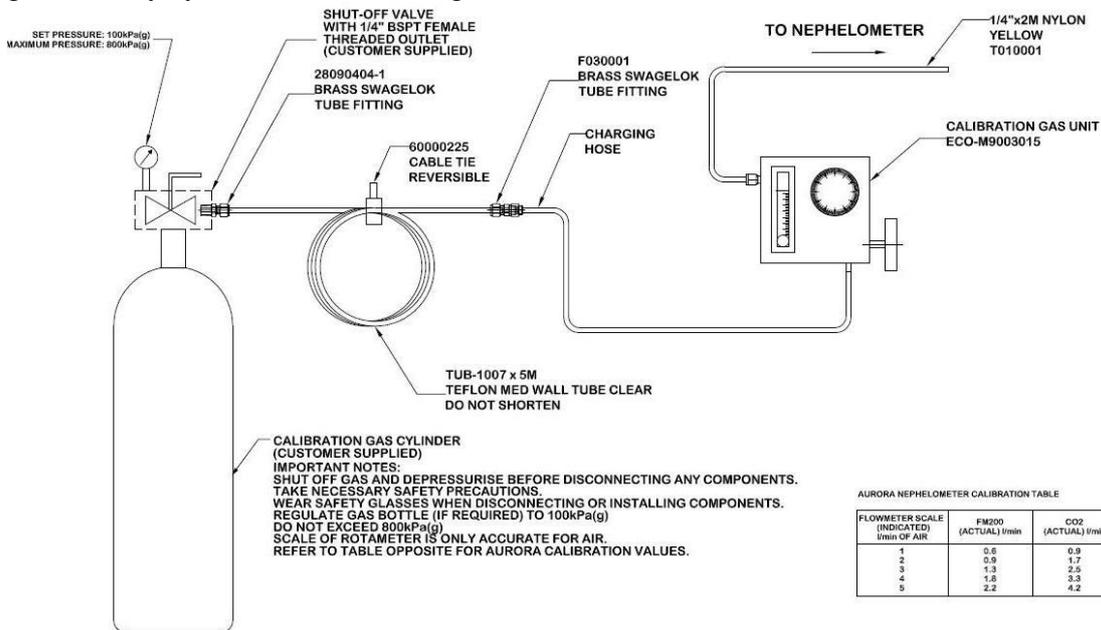


Figure 21 Span gas plumbing installation

Connect your calibration gas to the “span gas” port on the top of the Aurora. No connection is required for the Zero Air as the Aurora has its own internal filters.

2.2.2 Connecting the Power

The Aurora has an external, auto ranging power supply (100 to 250V AC, 50 or 60 Hz). This means that the Aurora can be connected to any domestic mains supply anywhere in the world via a standard IEC connector for the mains.

- The power cord should be connected to a general purpose power outlet.
- The outlet should have an earth pin for safety.
- The output of the power supply is 12v DC. The power supply has a 4 pin connector to connect to the 12v in connector on the Aurora.
- The on/off switch when pressed down will turn the instrument on.
- There is a green on indicator of the Power supply to show if the mains power is on or not.

2.2.3 External Cable Connections

Although the Aurora has its own internal data logging feature, some situations may require it to be connected to an external data logger. There are two ways to connect to a data logger.

RS232

Ecotech supply an RS232 cable with each Aurora 4000. This cable is suitable for connecting directly from the Aurora 4000 (Multi-drop port) to a standard 9 pin RS232 port found on most personal or laptop computers.

If you require a longer cable for your application, the following diagram shows how it can be made.

Note: When using cable lengths in excess of about 5 meters, you may need to reduce the Baud rate in order to reduce communication errors.

Section 5 contains more information on setting up the RS232 communications for data logger.

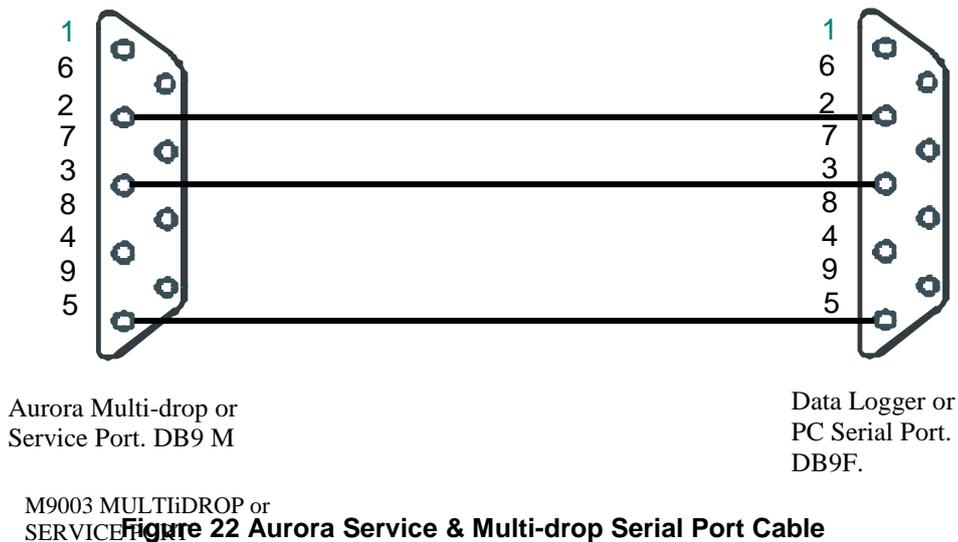


Table 3 Serial Port Pins and their function

Pin No	Function
1	CD (not used)
6	DSR (not used)
2	RD
7	RTS (not used)
3	TD
8	CTS (not used)
4	DTR (not used)
9	
5	GND
Shell	Chassis GND

2.3 Mounting/Siting

Siting Considerations

For additional information regarding siting, please consult your local Standards for siting guidelines.

The Australian Standard AS2922 requires that the sampling inlet be positioned:

- Between 2 and 5 metres above ground;
- At least one horizontal metre and one vertical metre from supporting structures or walls;
- With 120° of clear sky above the sampling inlet;
- With an unrestricted airflow of 270° around the inlet, or 180° if the inlet is on the side of a building;
- 20 metres from trees;
- With no boiler or incinerator flues nearby.

Mounting the Aurora

Note: The Aurora must be mounted so that the shortest possible length of tubing is used from instrument inlet to sample. This tubing should be vertical from instrument inlet straight up to sample i.e. no 90 degree kinks or horizontal sections as shown below.



Figure 23 Correct sample inlet connection

There are a number of ways in which the Aurora can be mounted. It can be seated on a bench top with the sample inlet running vertically through the roof, or mounted on a wall with the sample inlet running through the roof. An optional wall mounting bracket is supplied for easy mounting on the wall.

Attach the wall mounting bracket as follows:

- Determine where the Aurora is to be located and draw the centre line on the wall. This determines the positions of the sample and calibration gas inlets. Extend this line to the roof.
- Make sure there are no beams obstructing the inlets path through the roof.
- Mark and drill the holes for the wall mounting bracket.
- Secure the wall mounting bracket to the wall using two suitable fasteners. The bracket has two 7mm holes on its centre line to that effect. The two tabs should be at the bottom.

- Mark the position of the hole for the sample inlet tube and drill.
- The roof flange option can be used on the top of the roof to seal the sample inlet.

Note: When drilling holes, be sure to cover all open ports on the Aurora and supplied tubing. This will reduce cell contamination.

2.4 Instrument setup

When setting up the Aurora the following points should be completed:

- Set correct time (section 3.5.9)
- Clear data logger (section 3.5.10)
- Set standard temperature (section 3.5.7 “Normalise to”)
- Set automatic calibration interval (section 3.5.4.2 “Autocal intv”)
- Set Calibration gas type (section 3.5.4.2 “span gas” and/or “custom span gas”)
- Perform calibration (section 4.2)

3 Operation

With the Aurora 4000 installed correctly as outlined in the previous sections, it is now ready to be used. This section will discuss what to expect and how to configure the Aurora once it is powered up.

3.1 Startup

When the power switch shown in Figure 19 is switched to the ON position, the Aurora will go through its start-up sequence as follows:

Welcome screen

- The shutter solenoid will periodically click in and out of position every 30 seconds (dependant on amount of angles being measured).
- The display backlight will light up.
- The Welcome screen will provide information about the Aurora and its wavelength.

Ecotech Aurora 4000
Polar
Nephelometer

Instrument check

- The instrument runs through a diagnostic check of its systems checking the light sources, environmental sensors and photomultiplier. If any of these components fails the test it will be displayed with a fail on the left hand side of the instrument.

Ecotech Aurora 4000
Light Src chk Pass
Env Sensor chk Pass
PMT chk Pass

Warm-up

- The system calibration will commence.
- The instrument begins measuring the shutter count and backscatter shutter count with sample air, allowing light source to stabilise.

Ecotech Aurora 4000
Shutter Count 1 1.205
Shutter Count 2 1.432
Shutter Count 3 1.151

Main screen

- After the warm up is completed, the sample pump will start up.
- The screen will now enter the main screen
- The Aurora is now in MONITOR STATE and is sampling as described in section 3.3.

*Light source chk will normally show a fail for the first 10 seconds, this is performed on purpose to ensure that no measurements are taken during instrument check.

3.2 General operational information

3.2.1 Display panel and Keypad

The display panel and keypad (Figure 24) allows all current measurements to be displayed, settings to be entered and commands given. It consists of a 4 line LCD screen with 6 general use command keys/buttons.



Figure 24 Display panel and keypad

Up arrow key (▲)	Moves the cursor to the previous menu item or, in an input field, moves the cursor to the previous choice or increments the digit in a numerical field.
Down arrow key (▼)	Moves the cursor to the next menu item or, in an input field, moves the cursor to the next choice or decrements the digit in a numerical field.
Select	Selects the menu choice or selects the field for input.
Pg Up	Moves the cursor to the previous page or screen.
Exit	Leaves a field without making a change or returns the cursor to the main screen.
Enter	Confirms a menu item or a field selection to the microprocessor

Note:

- Only four lines may be displayed at a time. To reach options not on the screen use the up and down arrow.
- Units displayed on screen are set within the “report prefs” submenu (section 3.5.7) with the exception of σ_{sp} and σ_{bsp} , which always have units of Mm^{-1} (inverse megametres) and relative humidity, always in %.

3.2.2 Setting polar angle measurements

The polar nephelometer is flexible in the angles that can be measured. The user has the ability to select and the number and the degree position of polar angles being measured. To select these angles enter the → Angle select menu

1. Within this menu first choose the number of angles that will be measured, between 2 and 18 (remember 0° is always measured and must be the first angle).

<p>Note: Changing the amount of angles will delete all previous data, ensure all data has been downloaded before performing this action</p>
--

2. If the number of angles measured is increased, the new angles will be set at 90° automatically.
3. Individually set the degrees for each angle ensuring that they are in order and increasing in value (i.e. 1st = 0°, 2nd = 10°, 3rd = 20°, 4th = 30° etc). Note that the smallest non-zero angle that can be measured is 10°, (the truncation angle).

3.2.3 Display Backlight

When the Aurora is initially turned on, the Backlight on the LCD display will also turn on. However if the keypad is not used for approximately 3 minutes, then the Backlight will turn off automatically. The Display Backlight can be re-activated by pressing any one of the keys on the keypad.

3.2.4 Display Adjustment

On power up the display contrast will maintain the setting from its previous operation. The contrast can be adjusted by pressing either the up or down arrows on the keypad when on the main screen.

3.2.5 Navigating the menu system:

- Press the up arrow and down arrow to move the cursor amongst menu options.
- Press Select or Enter to activate a submenu or to perform an operation (these menu entries usually have → after them to indicate their type), or to edit an editable parameter. If the parameter is not editable then pressing Select or Enter will have no effect.
- Press Page up to return to the next highest level menu.
- Press Exit to return to the Information Screen.

3.2.6 Editing parameters:

- Press the up arrow and down arrow to cycle among the options for that parameter.

- Numerical parameters are usually entered digit by digit. Press the up arrow and down arrow to cycle among the options for that digit (including the decimal point). Press Select to move to the next digit to the right or Page up to move to the next digit to the left.
- Press Enter to save changes to the parameter.
- Press Exit to cancel changes to the parameter.

3.2.7 Obtaining readings

- The Instrument readings may be obtained through any of the following methods:
- Display panel (see section 3.2.1).
- Internal Data Logging (see section 5.1).
- Serial RS232 Communication Ports (see section 5.3).

3.3 Main screen

The main screen is displayed after the Aurora has passed through its warm-up or after pressing Exit while navigating the menu system. This screen is divided into two sections.

- The first section has three lines, the first line displays the angle that the current measurement is being performed at either 0 or an angle from 10-90. the second line lists which wavelength is being reported in that column and the third line displays the current measure of σ_{sp} .
- The second section includes the last line which display the current sample temperature (ST°C), Relative Humidity (RH%) and Barometric Pressure (BP). The value of each of these parameters is displayed immediately below on the fourth line.

The fourth line alternates after 16 seconds from the parameter names to the date and time. The date and time are only shown for 6 seconds.

Angle: 90 degrees		
635 σ_{sp}	525 σ_{sp}	450 σ_{sp}
1.256	2.346	1.498
Temp	Humidity	Pressure

Figure 25 main screen

3.4 Sampling

The Aurora 4000 performs continuous real-time sampling. The Aurora will provide updated measurements over the sampling time period chosen by the user (section 3.5.10 “Log period”). The units logged are:

- σ_{sp} 1: Scattering coefficient for 635nm (0 to 2000Mm⁻¹ or user defined full scale).
- σ_{sp} 2: Scattering coefficient for 525nm (0 to 2000Mm⁻¹ or user defined full scale).
- σ_{sp} 3: Scattering coefficient for 450nm (0 to 2000Mm⁻¹ or user defined full scale).
- ST: Sample air temperature in the cell (-40°C to 60°C).
- ET: Temperature within the Enclosure (-40°C to 60°C).
- RH: Sample air relative humidity (0% to 100%).
- BP: Barometric pressure in the cell (150 to 1150 mbar).

3.5 Menus and screens

To enter the Main Menu from the Information Screen press **Enter** or **Select**. The main menu gives access to the following submenus.

3.5.1 Readings

The Readings Submenu displays the current environmental sensor readings. The σ_{sp} reading is updated more frequently than the other parameters.

 σ_{sp} 1

Displays the current particulate scattering coefficient in Mm^{-1} for the red light source (635nm)

 σ_{sp} 2

Displays the current particulate scattering coefficient in Mm^{-1} for the green light source (525nm)

 σ_{sp} 3

Displays the current particulate scattering coefficient in Mm^{-1} for the blue light source (450nm)

BP

Displays the current air pressure inside the cell (mBar or atm).

Sample T

Displays the current sample air temperature inside the cell ($^{\circ}C$ or $^{\circ}K$)

Enclosure T

Displays the current enclosure temperature ($^{\circ}C$ or $^{\circ}K$).

RH

Displays the current sample air relative humidity (%).

3.5.2 System Counts

Dark Count

The measurement count taken when the light is off, used to offset incident light from reading. Should be 0 though 0-200 is typical (see section 1.4.2).

Shtr Count 1, 2 & 3

The shutter count take while the reference shutter is closed. This figure should be between 0.8M and 1.6M (see section 1.4.2).

Angle

Selects the current angle being displayed. You can edit this number to show information for angles 1-18.

Degrees

Displays the angle in degrees. This number cannot be edited here (go to Angle Select to change the degrees). It is displayed to remind you which angle you are viewing calibration information for.

Meas Count 1, 2 & 3

The measurement taken with light source on and reference shutter open. This figure will vary from 5k to 500k depending on particulate concentration (see section 1.4.2 for more details).

Meas Ratio 1, 2 & 3

The measure ratio is the ratio between the measure count and shutter count. (see section 1.4.2 for more details).

3.5.3 System Status

Major States

Monitr:	Normal monitoring mode
SysCal:	System calibration mode (During start-up or reset)
SpnCal:	Span calibration mode (During Full Calibration)
ZroCal:	Zero calibration mode (During Full Calibration)
ZroChk:	Zero check mode
SpnChk:	Span check mode
LeaChk:	Performing a leak check
ZroAdj:	Zero offset adjust (manual or automatic offset adjustment)

Minor states

Normal:	Normal Monitoring
ShtrDn:	Light path shutter moving into position and stabilizing
ShtrMs:	Reference shutter in place, taking shutter measurement
ShtrUp:	Reference shutter moving out of the way and stabilising

System Status

The System Status is the overall instruments status. If one status below fails then the system status will fail indicating that the entire system is not working.

Light Source

This status indicates whether the light source is working (pass/fail).

Enviro Status

The Enviro Status is the overall status of all the environmental sensors (RH Sensor, ST sensor, ET Sensor and BP Sensor). If one environmental sensor status fails then the Enviro Status will.

Shutter

This status indicates whether the reference shutter is working (pass/fail).

PMT

This status indicates whether the PMT is working (pass/fail).

Backscatter

This status indicates whether the Backscatter shutter is working (pass/fail).

Calibration

This status indicates whether the calibration is valid for the current set of angles. Whenever the number or value of angles is changed, a new calibration needs to be performed.

RH Sensor

This status indicates whether the Relative Humidity sensor is working (pass/fail).

ST Sensor

This status indicates whether the Sample Temperature sensor is working (pass/fail).

ET Sensor

This status indicates whether the Enclosure Temperature sensor is working (pass/fail).

BP Sensor

This status indicates whether the Pressure sensor is working (pass/fail).

ID Number

Lists the ID number of this unit

S/W Version

This menu item displays the version of software that the instrument is currently running. This is useful during some diagnostic and fault finding checks as well as for finding if an update to the software is required.

3.5.4 Calibration

The Calibration submenu has 5 submenus which cover all the aspects of calibration. These submenus allow the user to set the correct parameters to perform a calibration, initiate a calibration sequence and view the results from the previous calibration. For more information on performing calibrations, refer to section 4.

3.5.4.1 Activate Cal

Do full cal.

Performs a two point calibration using calibration gas and zero air. This sequence will adjust the calibration curve. The results are recorded as Last span ck & Last zero ck.

Do zero adj

Performs a zero adjustment on the instrument using zero air. The results are recorded as Last zero adj.

Do zero chk.

Performs a check but no adjustment of the instrument's zero using zero air. The results are recorded as Last zero ck.

Do span chk

Performs a check but no adjustment of instrument's span using calibration gas. The results are recorded as Last span ck.

3.5.4.2 Cal Settings

AutoCal Intv

Sets the automatic calibration type (see next) repeat period: Hourly, 3hrs, 6hrs, 12hrs, 24hrs, Weekly on a designated day or Off .

AutoCal Type

Sets the type of Auto Cal sequence: ZroChk, SpnChk, Z&SChk & ZroAdj.

Span gas

Sets the span gas to the type to be used during a full calibration: CO₂, SF₆, FM-200, R-12, R 22, R-134 or Custom.

Custom SpanG

If the span gas type Custom is selected above, then the Rayleigh multiplier is entered here for the type of gas you are using.

Cal min time

Sets the minimum time (in minutes) that any span or zero adjustment or check may take.

Cal max time

Sets the maximum time (in minutes) that any span or zero adjustment or check may take.

% Stability

Sets the target stability for any span or zero adjustment or check.

3.5.4.3 Last Tmp & Prs**Cal Span T**

Displays the temperature during the last span calibration.

Cal Span P

Displays the pressure during the last span calibration.

Cal Zero T

Displays the temperature during the last zero calibration.

Cal Zero P

Displays the pressure during the last zero calibration.

Adj Zero T

Displays the temperature during the last zero adjustment.

Adj Zero P

Displays the pressure during the last zero adjustment.

3.5.4.4 Wavelength

The following parameters are displayed within each of the Wavelengths (Red635, Green525, and Blue450).

Angle

Selects the current angle being displayed. You can edit this number to show information for angles 1-18.

Degrees

Displays the angle in degrees. This number cannot be edited here (go to Angle Select to change the degrees). It is displayed to remind you which angle you are viewing calibration information for.

Last span

Displays the σ_{sp} value (in Mm^{-1}) obtained during the last span check or calibration. If a full calibration is performed, it will display the σ_{sp} value before the calibration curve adjustment was made.

Span stab

Displays the % stability achieved during a span check or full calibration.

Last zero

Displays the σ_{sp} value (in Mm^{-1}) obtained after a zero check. If a zero adjust is performed, it will display the σ_{sp} value before the calibration curve adjustment was made.

Zero stab

Displays the % stability achieved during a zero check or zero adjust.

Cal M

Displays the gradient of the calibration line.

Cal C

Displays the intercept of the calibration line.

Wall Sig

Displays the calculated % of scattering as a result of wall scattering. This value is updated after a full calibration or zero adjust is completed. Refer to wall signal on page 9 for more details.

Cal span Y

Displays the measurement ratio at span calibration point

Cal zero Y

Displays the measurement ratio at zero calibration point

Adj Zero Y

Displays the measurement ratio at zero adjustment point

3.5.4.5 Env Sensors

The Environmental sensors menu will display a screen:

* Warning * Changes will re-calibrate environmental sensors immediately.

By scrolling down you can find the four environmental sensors readings. To calibrate these sensors all that must be done is to enter in the correct value, the correct value must be obtained from a calibrated temperature, humidity or pressure sensor (see sections 4.4.1 and 4.4.2).

Sample T Cal

Displays the current temperature within the sample cell, field is editable.

BP Cal

Displays the current barometric pressure, field is editable.

RH Cal

Displays the current relative humidity, field is editable.

ET Cal

Displays the current temperature within the enclosure, field is editable

Note: Do not change any of the above fields unless you are confident that the figure being entered is correct, inaccurate figures entered will result in faulty readings.

3.5.5 Angle select menu

Within this menu the number of angles being measured and the degree at which they occur can be set.

Important Note: Changing the number of angles or degree of any angle will result in the erasing of all currently stored data. Ensure all data is downloaded before changing settings

Important Note: Changing the number of angles or degree of any angle will also require the instrument to be recalibrated. The accuracy of any data measured without recalibration cannot be guaranteed.

Angle Count

Select the number of angles that will be measured, minimum 2 (0°, X°) maximum 18 (0°, X°, X° etc)

Angle 1

This angle is always set to 0°

Angle 2-18

Angles 2 up to 18 can be set at any angle starting from 10° up to 90°. Angle degrees must always increase starting from 0 in angle 1 and the largest angle being the last angle in the sequence

3.5.6 Control

The control submenu is where the user can set the sample heater properties. The configuration of this menu depends on which options are supplied and the application of the instrument.

Sample Heater

Sets the sample heater to either enabled (RH or XX°C) or disabled (No).

- If enabled (RH) the heater will maintain the sample air RH at a level less than that set in the Desired RH field (below).
- The heater can also be enabled by choosing a temperature at which the heater will maintain the sample at 0-50°C.
- If the sample heater is disabled then the sample air will not be heated.

Desired RH.

Sets the desired relative humidity range of the sample air: <40% (less than 40%), <50%, <60%, <70%, <80%, or <90%.

RH time on

Time in seconds that the sample heater is turned on for RH control.

3.5.7 Report Preferences

The Report preferences submenu allows the user to set the reporting preferences such as units and date format so that it is compatible with the local formats. These settings will alter the way the data is recorded in the internal data logger or via the RS232 interface.

Filtering

Sets the type of filtering used on the output data: Kalman (Adaptive digital filter, see section 2.3.1.5), MovAvg (fixed 30 second moving average filter) or None.

Date Format

Sets the date reporting format: D/M/Y, M/D/Y or Y-M-D (where D=Day, M=Month, Y=Year)

Temp.Unit

Sets the temperature unit:
°C, °F or K (degree Celsius, Fahrenheit or Kelvin)

Press.Unit

Sets the barometric pressure unit:
mb or atm (millibar or atmosphere)

Normalise to

Sets the standard temperature to which to normalise σ_{sp} readings: 25°C, 20°C, 0°C or None (do not normalise)

Temperature normalisation is used as follows:

- *European Union* 20°C
- *US EPA* 25°C
- *UK and Australia* 0°C

Ensure correct temperature is used as this will modify the data readings. Refer to section 1.4.3 for an example of how the readings can vary depending on the normalisation temperature.

3.5.8 Serial IO

The Serial IO submenu is where the user sets the parameters for the two RS232 serial ports (Multidrop and Service ports, Figure 19).

SvcPort Mode

This field allows the user to choose how the Serial port will be used. The options are:

- None: Serial port will not be used
- Reading : Data will be sent through the Serial port in the time periods specified within the “Reading Output” field below
- Menu: When enabled, the user can access the menu system using an ASCII terminal program. The user can navigate the menu remotely using the Up, Down, Left, Right arrow keys on the terminal.

Module Addr

Address for multidrop RS232 port: 0-7

MltDr Baud Rt

Communication Baud rate for multidrop RS232 port 1200 - 38400

MltDr Parity

Parity setting for multidrop RS232 port: None, Even, Odd

SvcPt BaudRt

Communication Baud rate for service port: 1200 - 38400

SvcPt Parity

Parity setting for service port: None, Even, Odd

Reading Output

Sends unpolled data through the service port when enabled in SvcPort Mode (See section 0.): None, 1 sec, 5 sec, 10 sec or 60 sec.

3.5.9 Adjust Clock

Note: When adjusting the clock ensure all data is downloaded before any changes are made.

To enter the current date and time: set the current date, the current time and remember to press enter on the Save time menu to have the date & time recorded.

A message “Setting clock...” will appear on the display and then return to the information screen.

Date	06/10/2007	Sets the current date
Time	11:02:09	Sets the current time
Save time	→	Records the date and time entered above

Note: Clear the data logger after changing time see section 3.5.10.

3.5.10 Data Logging

The data logging submenu allows the user to set the instantaneous data recording period of the internal data logger as well as clearing the memory of the Aurora 4000.

Log period

Sets the instantaneous data logging period.

All: Every measurement cycle is recorded (recommended)

1 minute: A single measurement is recorded every minute

5 minute: A single measurement is recorded every 5 minutes.

Clear DataLg

Clears all data stored in the data logging memory

Log data now

Records instantaneous readings when enter is pressed

3.5.11 Leak test

This screen will prompt the user to perform a leak check, select yes and follow the instructions on the screen and at the same time follow the procedure in section 6.3.6.

4 Calibration

Important Note: Changing the number of angles or degree or any angle will require the instrument to be recalibrated. The accuracy of any data measured without recalibration cannot be guaranteed.

The Aurora 4000 requires regular calibration against a known calibration source. The Aurora can perform 3 different calibrations of the measurement system:

- Precision Check (section 4.1)
- Full Calibration (section 4.2)
- Auto Calibration (section 4.3)

The Aurora also needs calibrations performed on various other sensors

- Pressure Calibration (section 4.4.1)
- Sample Temperature and Humidity Calibration (section 4.4.2)

Note: Before commencing any calibrations, make sure that the Aurora has been given 30 minutes to stabilise.

See section 6.2 for advice on calibration intervals

4.1 Precision Check

Precision checks should be performed on a regular basis (daily or weekly) using a calibration gas such as CO₂ (100% purity). The precision check is used to detect any drift in the instrument's calibration, it includes a span check and a zero check. Table 4 can be used to determine what action is required (if any) after the precision check.

Note: A precision check does not alter the calibration curve.

Table 4 Calibration check criteria.

Daily/Weekly Check	Calibration Tolerance	Action required
Zero Check	$\pm 2 \text{ Mm}^{-1}$	<i>Do zero adjust</i>
	$\pm 4 \text{ Mm}^{-1}$	<i>Invalidate data Do zero adjust</i>
Span Check	$\pm 1\% \text{ of span point}^*$	<i>Do full calibration</i>
	$\pm 5\% \text{ of span point}^*$	<i>Invalidate data Do full calibration</i>

* If calibrating with FM200, $\approx 220 \text{ Mm}^{-1}$ @ STP, then the $\pm 5\%$ limit would be $\pm 11 \text{ Mm}^{-1}$. The $\pm 1\%$ limit would be $\pm 2.2 \text{ Mm}^{-1}$.

4.1.1 Span check

The Span Check uses span gas to perform a span calibration on the Aurora without adjusting the calibration curve (only a comparison).

The Span check can be initiated as follows:

1. From the Calibration → Activate Cal sub menu select the “Do span chk”.
2. The following message will appear “Span check will commence within 30 seconds”
3. The span valve will open. Make sure the calibration gas is connected and flowing.
4. The instrument will return to the main screen and display Cal Stability, & Cal Time.
5. The span check will continue until
 - Cal Time has passed the Cal min time (section 3.5.4.2)
 - & Cal Stability has exceeded the % Stability set in the settings submenu (section 3.5.4.2).
 - Or if % Stability has not been reached, then the span check will continue until the Cal max time has elapsed (section 3.5.4.2).
6. After the span check has finished, the Aurora will update the values for Last span ck and Span ck stab in the Cal Param submenu.

4.1.2 Zero check

The Zero Check uses internally filtered particle free air to perform a zero calibration check on the Aurora without adjusting the zero point (offset).

The zero check can be initiated as follows:

1. From the Calibration → Activate Cal submenu select the “Do zero chk” command.
2. The following message will appear “Zero check will commence within 30 seconds”
3. Next the zero pump will turn on and the instrument will return to the main screen and display Cal Stability & Cal Time.
4. The zero check will continue until
 - Cal Time has passed the Cal min time (section 3.5.4.2)
 - and Cal Stability has exceeded the % Stability set in the settings submenu (section 3.5.4.2).
 - Or if % Stability has not been reached, then the zero check will continue until the Cal max time has elapsed (section 3.5.4.2).
5. After the zero check has finished, the Aurora will update the values for Last zero ck and Zero ck stab in the Cal Param submenu.

4.2 Full Calibration

The full calibration performs a two-point calibration on the Aurora. The span point uses calibration gas, the zero point use internally filtered particle free air. A full calibration is one in which both the span and zero points on the calibration curve will be modified. Due to the high stability of the Aurora this type of calibration only needs to be performed approximately every 3 months using calibration gas. Typically FM200 is used for the full calibration. A full calibration can be performed as follows once the setup is completed:

4.2.1 Setup

Make sure that the following options in the Calibration submenu are set (see section 3.5.4) before commencing a calibration.

1. Span Gas type: Set to the type of calibration gas you are using. Generally CO₂ or FM200.
2. Cal min time. Set the minimum time (in minutes) required to complete each calibration step (span or zero). Typically set to 15 minutes for a good calibration.
3. Cal max time. Set to the maximum time (in minutes) required to complete each calibration step (span or zero). Typically set to 20 minutes for a good calibration.
4. % Stability. Set the target stability for the calibration. A value of about 95-97% is recommended. If after Cal min time the calibration has not reached the target stability then the calibration will continue until it reaches the target stability or Cal max time, whichever comes first. Refer to sections 1.4.3 for further details.
5. Make sure you Calibration Gas is connected correctly and the valves and regulators have been opened. Refer to section 2.2.1 for details on connecting the calibration gas to the Aurora.

Note: Set the calibration gas flow rate to typically 3-4 lpm to calibrate the Aurora.

4.2.2 Procedure

1. From the Calibration → Activate Cal submenu select the Do full cal command. Immediately the following message will appear on the display. “Full calibration will commence within 30 seconds” after this the span gas solenoid valve inside the Aurora will open and the Main screen will display the following parameters (alternating):

Current σ_{sp} : **23.56**

The current σ_{sp} during the calibration.
(based on the old calibration curve)

Cal Stability: **97.50**

% Stability during the calibration.

Meas Ratio: **0.0138**

The Measure Ratio during the calibration.

Cal Time: **00:07:45**

The time the calibration has been running. (hh:mm:ss)

2. The span calibration portion of the full calibration sequence will end after:
 - Cal Time has passed the Cal min time (section 3.5.4.2)
 - and Cal Stability has exceeded the % Stability set in the settings submenu (section 3.5.4.2).
 - Or if % Stability has not been reached, then the zero check will
3. After the span calibration has finished, the Aurora will update the values for Last span and Span stab in the Calibration submenu as well as other vital calibration data. It will then automatically close the span gas solenoid valve and turn on the zero air pump ready for the zero calibration portion of the full calibration sequence.
4. The zero calibration will proceed the same as the span calibration. The information screen will display “ZroCal” as the major state. The bottom line will also display σ_{sp} , Cal Stability, Meas Ratio & Cal Time.
5. After the zero calibration has finished, the Aurora will update the values for Last zero and Zero stab in the Calibration submenu as well as other vital zero data. It will then turn off the zero air pump and turn on the sample pump ready for sample measuring.
6. After the sample measuring has commenced, the new calibration curve will be applied to the σ_{sp} readings.
7. Be sure to close the calibration gas cylinder after use to prevent any leaking.

4.2.3 Zero Adjust

The Zero Adjust performs a single point zero calibration on the Aurora. Using internally filtered particle free air, the zero adjust will adjust the zero calibration point (or offset) of the nephelometer. Although a zero calibration is calibrating against air rayleigh (14.82×10^{-6} m @ STP), the Aurora sets this point to zero (0) after the calibration. The zero adjust can be initiated as follows:

1. From the Calibration → Activate submenu select the Do zero adj command. Immediately the following message will appear on the display. “Zero adjustment will commence within 30 seconds” after this the zero pump will turn on and the information screen will be displayed.
2. In the same manner as the span calibration, the information screen will display σ_{sp} , Cal Stability, Meas Ratio & Cal Time.
3. The zero adjust will end after the Cal Time has passed the Cal min time and Cal Stability has exceeded the % Stability set in the calibration submenu. If the % Stability has not yet been reached, then the zero adjust will continue until the Cal max time has elapsed.
4. After the zero adjust has finished, the Aurora will update the values for last zero and zero stab in the Calibration → Parameters submenu as well as changing the zero offset on the calibration curve. It will then turn off the zero pump and turn on the sample pump ready for sample measuring.
5. After the sample measuring has commenced, the new calibration curve will be applied to the σ_{sp} readings.

4.3 Auto Calibration

The Aurora can be set to perform calibrations automatically at regular intervals. The check interval can be set in the Calibration submenu (Refer to section 3.5.4) under the AutoCal Intv parameter. The calibration can be set to calibrate: hourly, 3, 6, 12, 24hrs, weekly, off or on a specific day of the week. The Autocal Type can be set to: zero check, span check, zero & span check, or zero adjust (as discussed in section 4.1.1, 4.1.2 and 4.2.3).

4.4 Sensor Calibration

Equipment Required.

- Calibrated Temperature Probe.
- Calibrated Relative Humidity Sensor or Psychrometer.
- Calibrated Barometric Pressure Sensor.

4.4.1 Pressure Calibration

1. Disconnect the sample pump and allow the pressure reading to stabilize.
2. Obtain the current barometric pressure reading from a Calibrated Barometric Pressure Sensor (BPS).
3. Enter the Calibration → Env sensors menu, scroll down until BP Cal field.
4. Enter the Barometric pressure reading obtained with BPS into the field.
5. Reconnect the sample pump.

4.4.2 Sample Temperature and Humidity Calibration

1. Open the Aurora front panel by removing 2 screws from face edge
2. You may need to follow the steps (1 to 5) from section 6.3.2 to remove the light source to gain access to the sensor.
3. Remove the Sample Air Temperature sensor from the cell by first removing the cable (unscrew nut 1 anti-clockwise and pull)
4. Release the sensor by unscrewing nut 2 (anti-clockwise) as shown below and pull out.

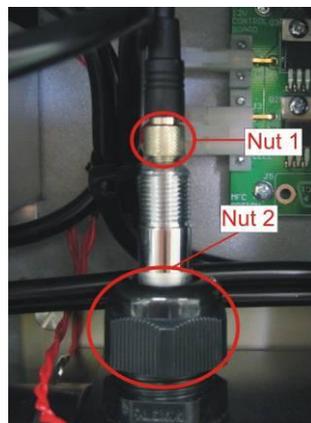


Figure 26 Temperature/Humidity sensor

5. Replace the nut 1 cable and allow the Aurora Air temp and Humidity readings to stabilise.
6. Place a calibrated Temperature Probe close to the Air Temperature Sensor and allow them to stabilise to ambient room temperature/humidity. Then take an ambient reading.
7. Record the Temperature and humidity
8. Enter the Calibration → Env sensors menu, scroll down and enter readings into their respective fields Temperature = Sample T Cal , Humidity = RH Cal.

Note: Perform span and zero calibration after environmental sensor calibration

4.5 Calibration check via External IO/RS232

4.5.1 Initiating a Calibration via the External IO

The Aurora has a 25 pin External IO connector which is used, not only for connecting the analogue outputs, but also for connecting digital inputs. There are two designated digital inputs used for initiating the Zero and Span Measure modes. These inputs are ideally suited for external data logging devices which control the calibration sequences. There are no menu settings or software setup required to activate these inputs, just hardware.

Activating Digital inputs

The external inputs for the span and zero measure control require a contact closure or open collector type of input as shown in Figure 27. The span or zero measure will commence once either of the two pins on the External IO connector are closed or active low. The input signal must be:

Low (on) < 0.8V, or 2V < High (off) < 5V

These pins have been labelled DOZERO and DOSPAN in Figure 27.

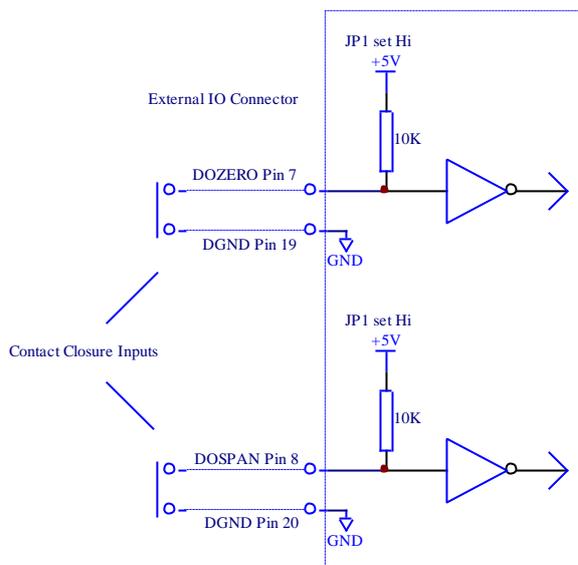


Figure 27 External Span & Zero Control

Zero Measure

The Zero Measure mode is activated using the DOZERO digital input.

1. As soon as the DOZERO input is activated the instrument will go into zero measure mode. The sample pump will turn off and the zero pump will turn on, pumping particle free zero air into the measurement cell.
2. During the Zero Measure, the main screen will display “Zero Measure” on the top line.
3. The Zero Measure will continue for as long as the DOZERO input is activated. As soon as this input is de-activated, the Zero Measure will stop by turning off the zero pump and turning on the sample pump. This procedure is only a check, no adjustment is made to the calibration curve

Span Measure

The Span Measure mode is activated using the DOSPAN digital input.

1. As soon as the DOSPAN input is activated the instrument will go into Span measure mode. The sample pump will turn off and span gas solenoid valve will open, allowing calibration gas to pass into the measurement cell.
2. During the Span Measure, the main screen will display “Span Measure” on the top line.
3. The Span Measure will continue for as long as the DOSPAN input is activated. As soon as this input is de-activated, the Span Measure will stop by closing the span gas solenoid valve and turning on the sample pump. This procedure is only a check, no adjustment is made to the calibration curve

4.5.2 Initiating a Calibration via the RS232 Interface

The following commands can be used to initiate a calibration via the multidrop serial port: (The multidrop address is 0 in this example).

DO0001<CR> Sets the Aurora 4000 into span measure.

DO0000<CR> Sets the Aurora 4000 back to sample measure.

DO0011<CR> Sets the Aurora 4000 into zero measure.

DO0010<CR> Sets the Aurora 4000 back to sample measure.

Refer to section Appendix A for more details on these commands and others.

4.6 Calibration Gases/Standards

4.6.1 Zero Air

The Aurora requires particle free air as its source of zero air. This is generated internally using the zero pump and a series of filters to remove all particulate matter. There is no need for any external connections to the zero air port. The zero point on the Aurora is also called Air Rayleigh which is equal to $14.82 \times 10^{-6} \text{ m @ STP}$, however the measured σ_{sp} will read zero (0) at this point. All other measurements are made relative to Air Rayleigh.

4.6.2 Span Gas

The unique advantage of calibration (span) gases used in nephelometers is that they are stored in their liquefied form. Hence there is no need for expensive gas dilution systems. The calibration gas can be connected directly to the Aurora as specified in section 2.2.1. The other advantage is that each gas type has a unique σ_{sp} relative to Air Rayleigh. Hence the user when calibrating only has to select the correct span gas type and does not have to calculate dilution ratios and concentrations. The Aurora 4000 does everything for you.

The Aurora supports CO₂, SF₆, FM-200, R-12, R 22 and R-134 as the span gas types. See section 1.4.3 for further details on calibration gas constants for these gases. There is also the option of entering the Rayleigh multiplier of an unlisted calibration gas (or Custom Gas) in the calibration menu.

Ecotech use CO₂ and FM-200 when calibrating the Aurora 4000s in the factory. FM200 is a trade name and may also be known as Heptafluoropropane, CF₃CHF₂CF₃, HFC-227ea.

It is best to check with your local regulations and standards to see which calibration gas is to best used in your location.

5 Downloading data

There are two main ways of recording data from the Aurora 4000 which are mentioned in this manual. These are:

- Internal Data Logging Facility
- External Data Logging using RS232 interfaces

Note: A laptop computer is a practical way of downloading the data from a Nephelometer that is in service in the field. If your laptop does not contain a serial port then a U.S.B. – serial adaptor should be used. It is highly recommended that the easysync U.S.B. – serial adaptor be used for this function as it has been widely tested with all Ecotech products, works effectively and can be purchased from Ecotech.

5.1 RS232 Interface

There are two RS232 interface connections available on the Aurora. They can be used for such things as downloading historical data, retrieving instantaneous readings or controlling certain features of the instrument. The following section will discuss the various functions of the Multidrop Port and the Service Port.

5.1.1 Multidrop Port

The multidrop serial port is the main port used for external data logging and control. This port responds to the majority of RS232 commands. The term multidrop is a term used to denote a parallel connection of multiple RS232 devices. All receivers share the same receive line that comes from a single master computer. Likewise, these multiple devices share the same transmit line which goes back to a single master computer. This method is ideal for attaching multiple instruments to a single master computer where the number of available serial ports are limited. All the instruments can be connected to a single multidrop cable. This type of configuration is often referred to as a daisy chain.

The integrity of this method relies on a number of important rules being followed:

- Each instrument in the multidrop must have a unique Module Address that is programmed into the unit before attaching to multidrop cable. Aurora 4000 instruments consume 4 module addresses; the one you assign and the next three. Therefore you can only have at most two Aurora 4000 instruments in the same daisy chain, one at address 0 and one at address 4.
- After a command is sent by the master, the master must then wait for a response. Only after a reasonable time-out period should the master send another command.
- The multidrop master must include a time-out mechanism in the event that the Module Address sent with the command is garbled.
- The master must correlate the unit response with the Module Address sent in the command to know which unit in the multidrop is responding.
- Any command that would cause two units on the multidrop to respond at the same time must be avoided. If more than one unit attempts to respond on the common transmit line, a "data collision" will occur destroying both messages.

5.1.2 Service Port

The service serial port is not a multidrop port and will not respond to any multidrop commands. It is primarily used factory testing.

5.1.3 Establishing Communications

The first step in establishing communications with the Aurora is to connect a computer or terminal to the Multidrop RS232 port. The default serial configuration for serial port is 9600, 8, N, 1 (9600 baud, 8 bits, no parity, and one stop bit). If you need to change the serial configuration from the default, use the Serial IO Submenu. Also make sure that the Module address is set to a unique value (the default is "0"). Once the instrument has been connected, use a communication package such as Hyper Terminal to establish communications with the instrument. Use one of the commands mentioned in section Appendix A to test the communications.

5.2 Internal Data Logging

5.2.1 Configuration

The internal Data Logging capabilities of the Aurora are very simple to operate. As long as the instrument is operating, the data logger is recording the data. The user has only to select the instantaneous data reporting period from the Data Logging menu (section 3.5.10). These are:

- 5 minutes
- 1 minute
- All, which captures every single measurement taken

The time period covered depends on the number of angles measured. When capturing every 1 or 5 minutes, the amount of time covered will decrease as the number of angles increases. When capturing all data, the amount of time covered will actually increase as the number of angles increase, because the overhead (temperature, humidity) stored with each cycle will occupy less memory.

The data logger memory is cyclic, so that once it is full it will rewrite over the earliest data records. The memory is also battery backed so that data will not be lost when the power is off.

The data logger memory should be reset at the start of a sampling episode and when the date is changed. When data is downloaded, it will only be taken from that time onwards.

Note: When the list of angles being measured is changed, the data logger memory will be erased for you.

The Log Data Now function allows the user to manually test the data logger by recording data instantaneously when the enter key is pressed.

The parameters recorded in the data logger are as follows and cannot be changed:

Time (in seconds), Status, Type, [$\sigma_{sp 1}$, $\sigma_{sp 2}$, $\sigma_{sp 3}$ ($m10^{-6}$),]* ST (°C), ET (°C), RH (%), BP (mbar)

* This section (between the []) is repeated for each angle being measured.

5.2.2 Data Downloading

Once you are connected to the Aurora 4000 over the multi-drop port, there are a few simple commands to access the data logger memory. These commands are discussed in detail in Appendix A, but an overview is provided here:

- ^T Tells the Aurora 4000 to listen for additional commands.
- ***D Downloads all the new data.
- ***R Rewinds to the beginning of the data. The next ***D command will download all the stored data, not just the new data since the last time you downloaded.
- ***B Erases the data log. This happens automatically whenever you change the list of angles being measured. NOTE: This command has 3 asterisks, which differentiates it from the reboot command (which has 2 asterisks).

5.2.3 Data Downloader Software

With the Aurora Data Downloader installed on your computer, the internal data logged by the Aurora can easily be downloaded to a text file where it can then be imported into a spreadsheet program such as Excel.

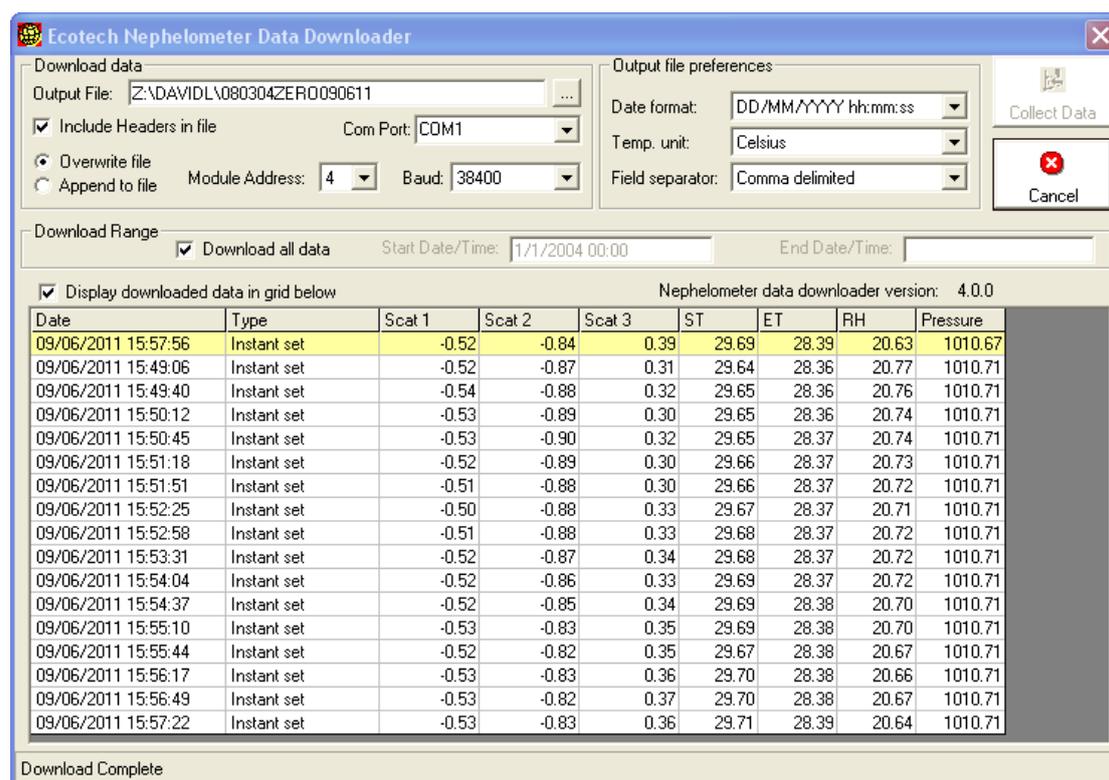


Figure 28 Aurora Data Downloader

- Open the Aurora Data Downloader software where the following window is displayed as in . The bottom left hand corner of the window displays the current status.
- Ensure that the Aurora is connected directly to your computer via the Nephelometer Multi-Drop port and your computer’s serial port.

- Enter in the “Output File” the name of the file you wish to save data to, and select whether you wish to overwrite or append to the file, if it already exists. Click the “...” button to browse for your output file. For importing into Excel, we recommend using the “txt” file extension for your output file.
- Selecting ‘Include Headers in file’ will write a single line at the start of the download, with the column names, including all the angles and wavelengths. This makes interpreting the data in third party programs such as excel much easier. It is essential to enter the correct ‘Module Address’ (found in the Serial IO menu of the Aurora 4000) for this option to function correctly.
- Select the appropriate Com port to be used by your computer.
- Set the Baud rate in the Data Downloader to match the setting on the Multi-Drop port on your Aurora (“Serial IO” menu).

We strongly recommend using a baud rate of 38400 for fastest downloading speed.

- Select the appropriate Date Format, Temperature Unit and Field Separator. These settings will affect the format of the downloaded file. The Date Format is important if you’re going to be importing the downloaded data into a spreadsheet such as Excel.
- Select either the “download all data” box or enter the start and end date for the period of data you wish to download.
- Select the box labelled “Display downloaded data in grid below” if you want to see the data for the full (0°) scattering as it is collected.
- When all is ready, click the “Collect Data” button. You will see the window below fill up with data. The data will also be saved to the file.
- When downloading is complete, you will be asked whether you wish to clear the data store. If you collect data periodically and don’t specify the download window, it’s recommended that you clear the data each time, so you won’t have to download the same data over and over again.



Figure 29 Clear the data store window

- If the Nephelometer is not connected or the serial IO settings are not correct, an error will be displayed when you try to collect data.

5.2.4 Importing Data into MS. Excel

- To import your data into Excel, run Excel and select File > Open. Then choose to open files of type “Text files”, and select your data file.

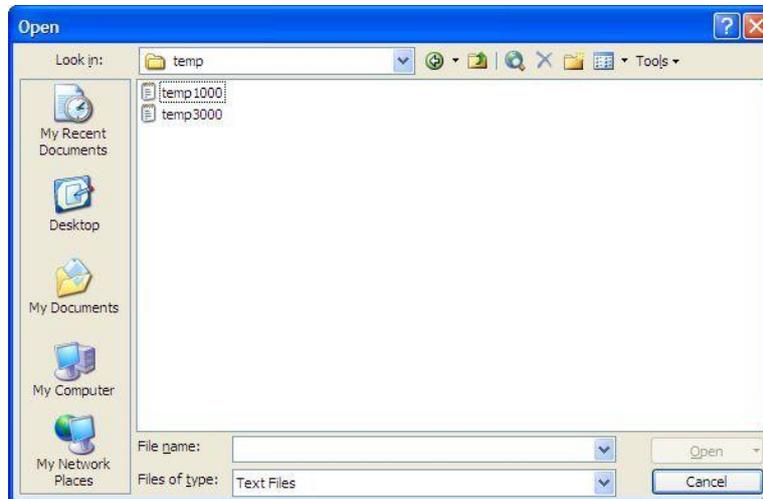


Figure 30 Open Window.

- The Text Import Wizard will appear.
- Set the settings to Delimited. Press the “Next” button.

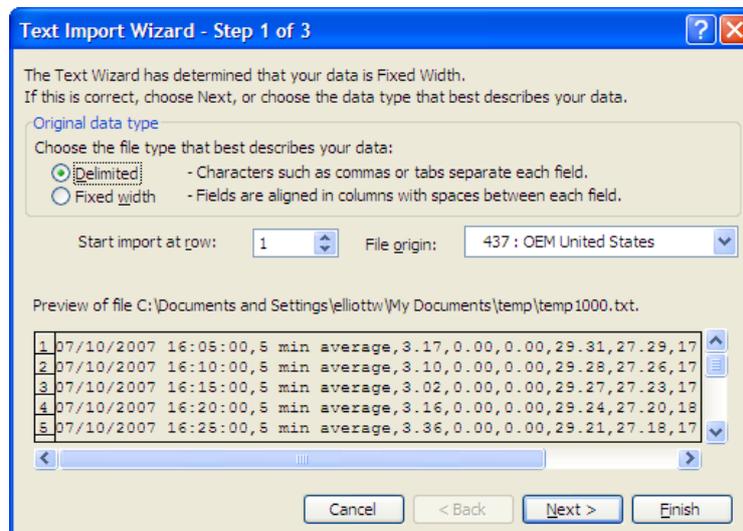


Figure 31 Step 1.

- Include Comma and Tab as the delimiters for the data. Press the “Next” button.

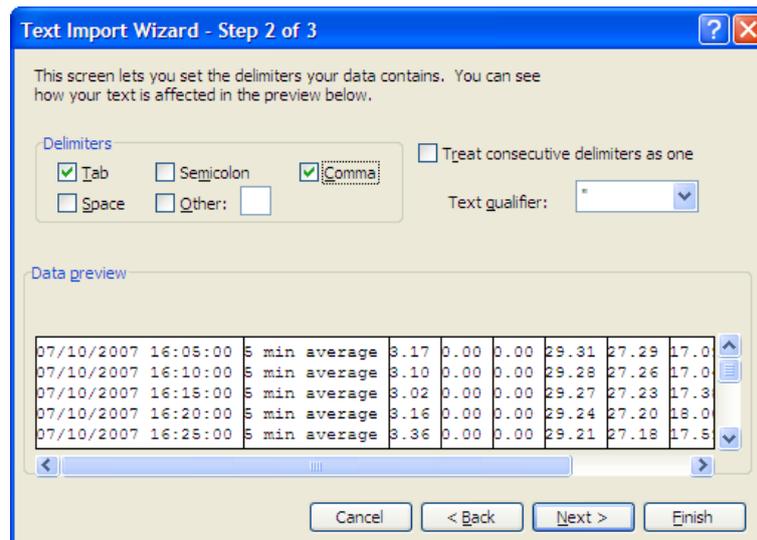


Figure 32 Step 2.

- Set the first row to Date format.
- Press the “Finish” button.

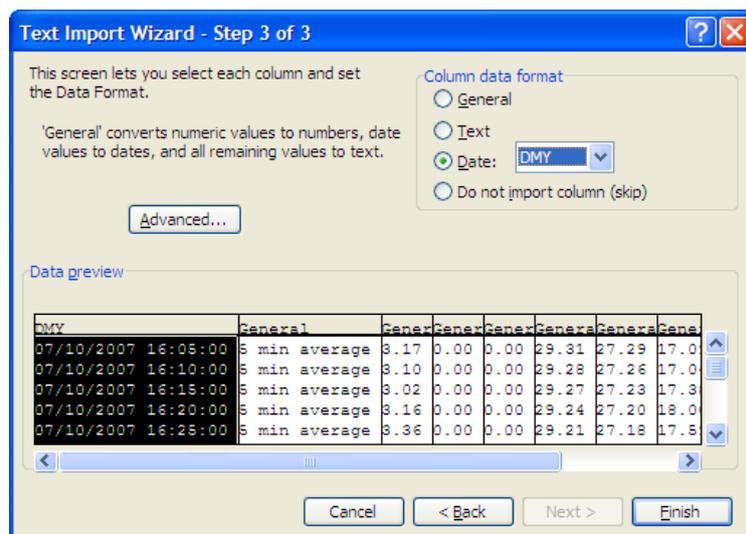


Figure 33 Step 3.

- Your data should be imported into Excel, as shown below in Figure 34.

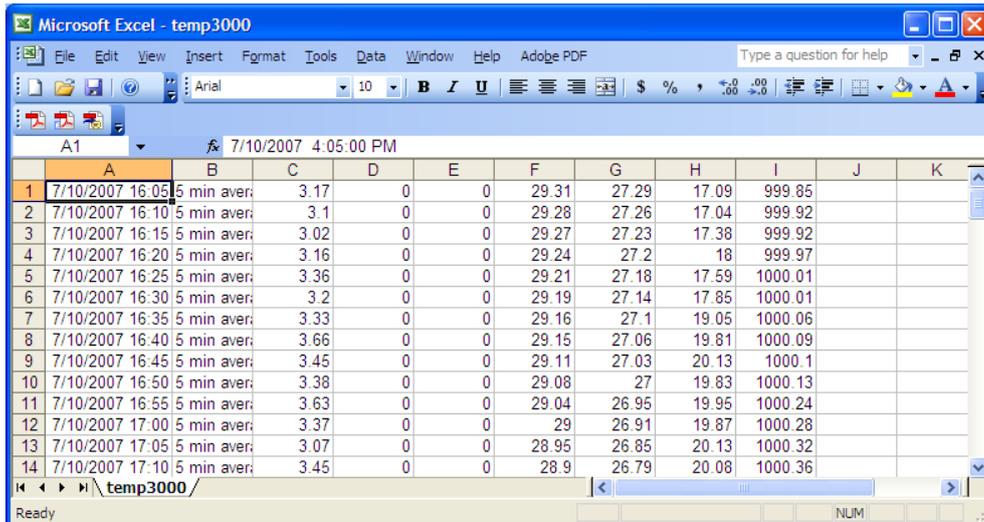


Figure 34 Imported Data.

- Note that if dates fail to import correctly, you may have to change your regional options. This can be done from the Control Panel > Regional and language options.
- Note that in Control Panel > Regional and language options > Customize, you should make sure that the Decimal symbol is set to a Period ”.” Not a Comma”,”. This will make it easier to download comma separated variables.

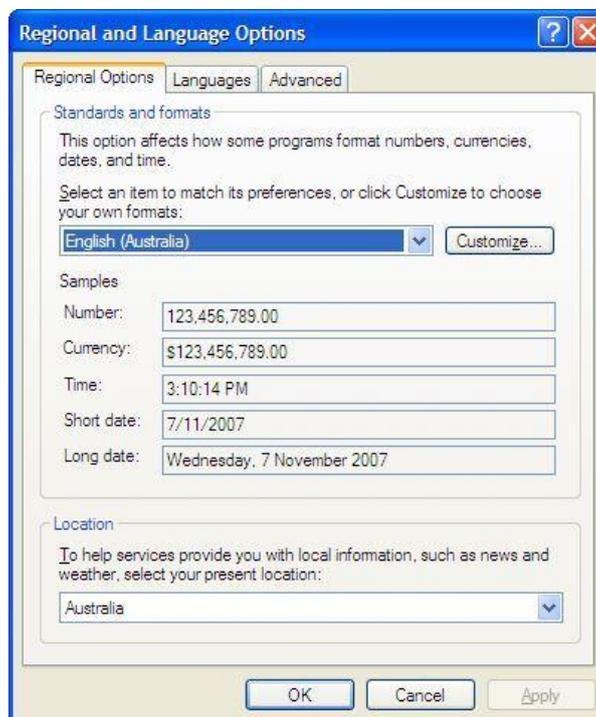


Figure 35 Regional Settings.

5.3 External Data Logging

There are a number of ways connecting the Aurora 4000 to an external data logger. The best way is by using the RS232 interface as there is no degradation in the transfer of data. The Ecotech AQMS & WinAQMS Data Acquisition Systems can be easily configured to log any of the Aurora 4000 parameters via RS232 Multidrop communications.

Using WinAQMS

For details on connecting the Aurora 4000 to the WinAQMS Data Acquisition System, please refer to the WinAQMS manual.

Using AQMS

For details on connecting the Aurora 4000 to the 9400 Data Acquisition System, please contact Ecotech for further details.

Other Data Logging Software

If you are using some other data logging software for logging the Aurora 4000 then please refer carefully to the RS232 commands listed in Section 6 of this manual as to whether the software is compatible.

Ecotech takes no responsibility for data integrity when the Aurora is used with 3rd party software which does not meet the guidelines set out in Section 0 of this manual.

5.4 Upgrading the Aurora 4000 Firmware

As improvements are made to the Aurora, these can be easily passed on to the user by updating the firmware (software operating within the Microprocessor board). To update your Aurora, you will need the Ecotech Firmware Updater Program. This is available on the Utilities CD supplied with your instrument or through the Ecotech website www.ecotech.com.au. Install this software on a Windows based computer with a COM port. Just follow the instructions on the installation screens to install this software.

The firmware file will have the “.sx” suffix. (eg. Aurora 2.10.SX). V2.10 refers to the version number. To check whether you have this version already installed on your instrument, scroll down to the bottom of the “main menu” on your Aurora.

To update the firmware on the Aurora 4000:

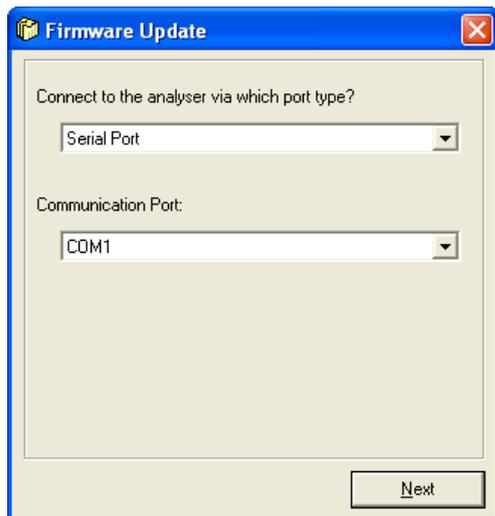


Figure 36 Communications Window.

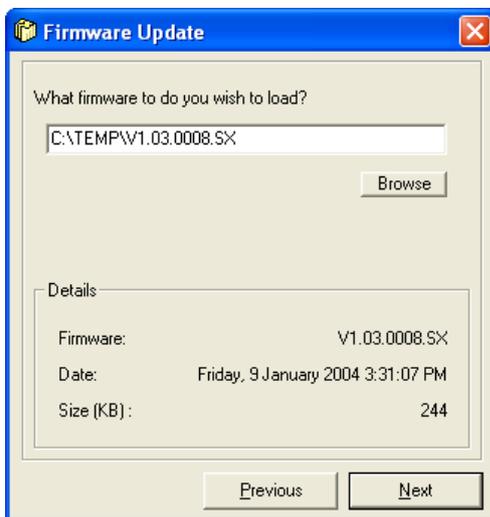


Figure 37 File Window.

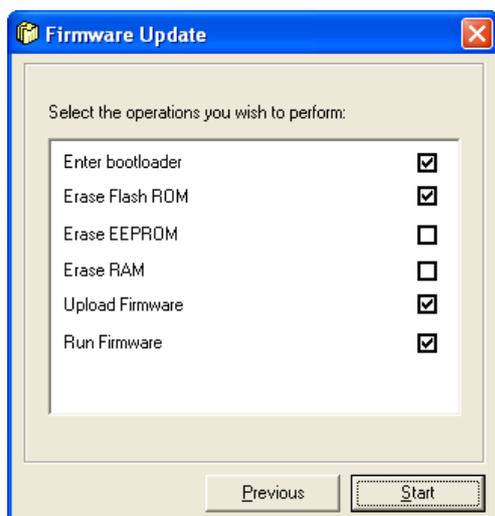


Figure 38 Operations Window.

1. Run 'Firmware Updater' from the 'Start - Programs - Ecotech - Firmware Updater' menu.
2. Connect the Nephelometer to the computer using a standard serial cable (you must connect directly to the Multidrop port).
3. Select 'Serial Port' and the COM Port on the computer from those listed on the Firmware Update screen as shown in Figure 36.
4. Press the Next Button to move to the next menu.
5. Using the “Browse” button, locate the firmware file (.sx) which you wish to update the Aurora with.
6. Verify its details in the Details window as shown in Figure 37
7. Press the Next Button to move to the next menu.
8. Turn off your Aurora, and connect it directly to your computer via the Multi-Drop port and your computer’s serial port. There is no need to change any baud rates.
9. Make sure that all the boxes as shown in Figure 38 are checked.
10. Press the “Start” button.

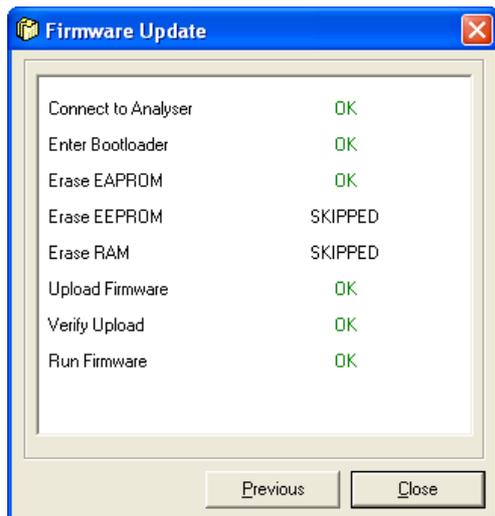


Figure 39 Data Transfer Window.

11. Turn on Aurora.
12. The Firmware Updater window will show each step as the firmware is uploaded. **DO NOT** turn the analyzer off until the 'Close' button is enabled as shown in
13. Your Aurora should now be running with the updated firmware. Confirm this in the sys status menu.

After the firmware update, it is recommended that you do the following:

- Reset the Aurora by turning the power off then on again.
- Reconnect any cables which may have been removed to perform the update.
- Perform a full gas calibration.
- Clear the Aurora's data log.

The Aurora 4000 is now ready for use.

6 Maintenance

The following outlines a periodic maintenance schedule for the Aurora 4000. This schedule is based on experience under normal operating conditions, and may need to be modified to suit specific operating conditions. It is recommended that this schedule be followed in order to maintain reliable, long-term operation of the instrument.

6.1 Maintenance tools

To perform general maintenance on the Aurora, the user will be required to carry the following equipment:

Equipment Required.

- Phillips Head Screwdrivers.
- Flat ended Screwdriver.
- Adjustable wrench.
- Black cloth or plastic bag.
- Bright LED Torch.
- CRC CO Contact Cleaner.
- Lint and grease free tissues or cloth.

Consumables

- Zero Air Pump inlet filter DFU (95%) pt: 036-040180
- Zero/Span Fine filter DFU (99.5%) pt: A-FIL-1050

Service Kit (Optional)

The optional service kit (part number H020335) contains the following items. All of these parts may or may not be used in the 12 monthly maintenance depending on the condition of the instrument. O-Rings need only be changed if they look damaged or they are the cause of a leak

Item	Qty	Part Number	Description
1	1	FUS-1156	5A T250V Fuse
2	1	TUB-1015	Black Carbon Tubing 50mm
3	1	ZRU-22006361	V-Ring V10A for PMT
4	4	O010015	O-RING 1/4ID VITON for Cell End Nuts.
5	1	25000420-2	O-RING for Light Source
6	4	ORI-1007	O-RING BS148 NITRILE for Cell Housing
7	2		AA Alkaline Batteries 1.5V
8	2	FIL-1050	DFU 99.5% for Zero/Span Fine filter and Zero Air Pump.
9	5	C060002	Lint Free tissues, 5 Sheets.

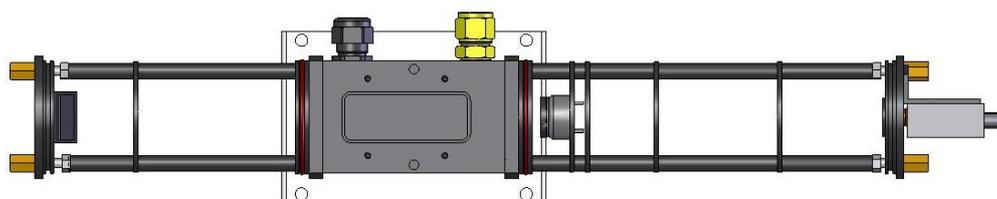


Figure 40 Aurora 4000 O-Ring Locations

6.2 Maintenance schedule

Table 5 Maintenance schedule

Interval *	Item	Procedure	Page
Weekly	Precision Check	Check	Section 6.3.1
Quarterly	Sample inlet & Bug trap	Inspect/Clean	Section 6.3.3
	Full Calibration	Perform	Section 4.2
	Clock	Check	Section 3.5.9
6 Months	Zero Pump Inlet Filter	Inspect/Replace	Section 6.3.4
	Zero / Span Fine Filter	Inspect/Replace	Section 6.3.5
	Measurement Cell	Clean	Section 6.3.2
	Leak Check	Perform	Section 6.3.6
	Zero Noise Check	Perform	Section 6.3.11
Yearly	Batteries	Replace	Section 6.3.7
	Optical Chamber	Inspect clean	Section 6.3.10
	Pneumatics	Clean	Section 6.3.8
	Light Source	Check/Adjust	Section 6.3.12

* Suggested intervals for maintenance procedure may vary with sampling intensity and environmental conditions.

6.3 Maintenance procedures

6.3.1 Precision check

To ensure the instrument is running appropriately precision checks must be performed every week. A precision (calibration) check involves performing a span and zero calibration check (which may have been performed automatically over night or manually), then, entering the Calibration menu and checking the Last zero ck field, Zero ck stab and Last span ck field

1. The Last zero ck field should be $0 \pm 1 \text{ Mm}^{-1}$
2. The Last span ck field should be within $\pm 5\%$ of span value.
3. The zero ck stab and span check stab fields should be above that entered into the stability field within the calibration menu

6.3.2 Measurement Cell cleaning

If this is part of the 6 monthly maintenance, the cell does not need to be removed. If it is part of the 12 monthly maintenance, then follow the procedure in section 0 where the optical chamber is removed.

1. Turn off instrument
2. Undo the two screws located on the front panel of the instrument (1) and lower the Aurora front panel
3. Unplug the light source ribbon cable connected to the side of the light source as well as the 2 pin red and black cable connected to the top of the light source.
4. Unscrew the 4 screws holding the light source in place (2)
5. Carefully slide the light source straight out by lightly resting the light source on the bottom surface of the cell opening. This will prevent the backscatter shutter from catching on the top of the cell opening and bending. Place the light source in a safe position facing up.

Note: Ensure that the O-ring within the light source is not lost or misplaced.

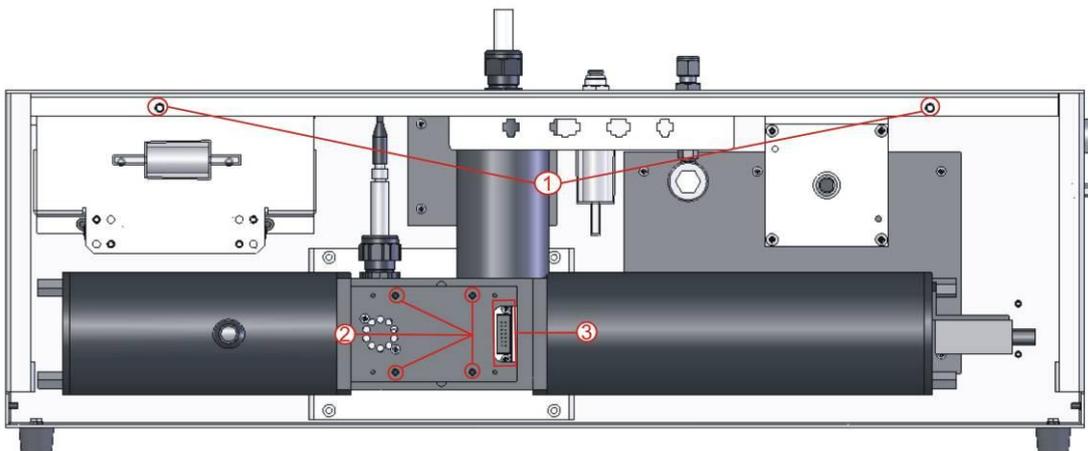


Figure 41 Aurora internal components

6. Use warm water on a lint free tissue to wipe the insides of the cell paying special attention to the bottom right section and the walls.

Note: Do not leave finger prints or any residue within the cell

7. Leave the cell open until all internal surfaces are dry of water
8. Carefully replace the light source, cables, and front panel of the instrument.
9. Always perform a leak check and full calibration after removing the light source.

6.3.3 Sample inlet and bug trap clean

1. Remove the insect trap from the inlet.
2. Turn the two white handles so that they are not holding the central filter in place (see Figure 42).



Figure 42 Insect trap removal

3. Remove the central filter and clean both the inner and outer filters with warm water. Allow them to dry.
4. Place the inner filter back into the insect trap, return the handles to their original position and return the insect trap to the inlet.

6.3.4 Coarse filter

1. Open front panel.
2. Remove DFU from the quick fit fitting and the clear tubing ()
3. Replace with a new DFU 95% (pt: 036-040180) or you can use the fine filter (FIL-1050).
4. Close case.

Note: The 6 month interval is given as an indication only. More frequent filter replacements may be required depending on the instrument location.

6.3.5 Zero/Span fine filter

1. Open front panel.
2. Remove DFU from the clear tubing ()
3. Replace with a new DFU 99.5% only (pt: A-FIL-1050)
4. Perform a leak check
5. Close case.

Note: The 6 month interval is given as an indication only. More frequent filter replacements may be required depending on the instrument location.

6.3.6 Leak check

1. Should be performed earlier than scheduled if a high zero reading is observed. (greater than 1Mm^{-1}). Should also be performed if any maintenance work has been conducted.
2. Open case front (Section 6.3.2)
3. Disconnect the external sample tubing from main sample inlet (2).
4. Remove tubing from exhaust fan (1) and place sample tubing on main sample inlet (2) as shown in .
5. Enter Leak check menu on main menu, screen will prompt you to connect the exhaust to the inlet, once this is done (step 4) change leak check field to yes and press enter.
6. Instrument will activate the zero pump and pressure will increase. Wait as instrument checks for a slow leak over 5 minutes.
7. If the screen gives the result “leak test pass” then there are no leaks and the tubes should be returned to normal.
8. If the leak test fails and “Low leak” is displayed then check that the tubing between the cell and sample inlet is either damaged or not plugged properly.
9. If the leak test fails and “Press.Leak” is displayed there is a leak within the cell (including tubing).

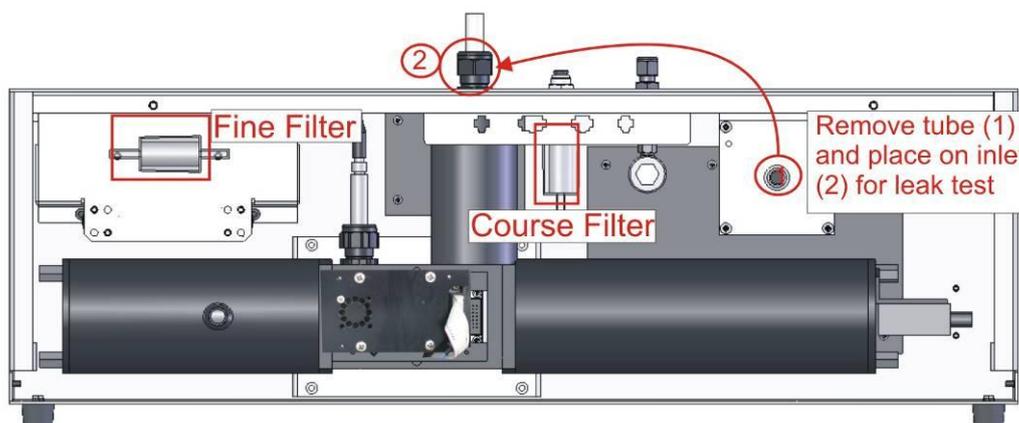


Figure 43 Aurora with Filters highlighted and leak test setup shown

6.3.7 Battery replacement

Replace the two AA alkaline back-up batteries. This is best done with the power connected so that the clock and logged data are not lost.

Note: It is recommended that the backup batteries are removed if the Aurora is to be powered down for more than a few months. Save the logged data before you remove the old batteries as it will be lost.

6.3.8 Pneumatics cleaning

This should be performed only when the optical chamber is removed from the instrument for cleaning. (See section 0)

1. Follow the procedure from section 0 to remove the optical chamber.
2. Remove black exhaust tubing from the exhaust fan (1) and the optical chamber (2) as shown in Figure 44
3. Unscrew the black gland on top of the instrument (4)
4. Remove the sample heater from its connector (5) and gently pull the main inlet down until it is out
5. Clean both the inlet and exhaust tubes in warm water (do not put main inlet under water, only clean inside of tube). Do not use any solvents or chemicals for cleaning.
6. Leave to dry then replace all components back into instrument as they were found. This includes the optical chamber after it has been cleaned.
7. Perform a leak check and full calibration

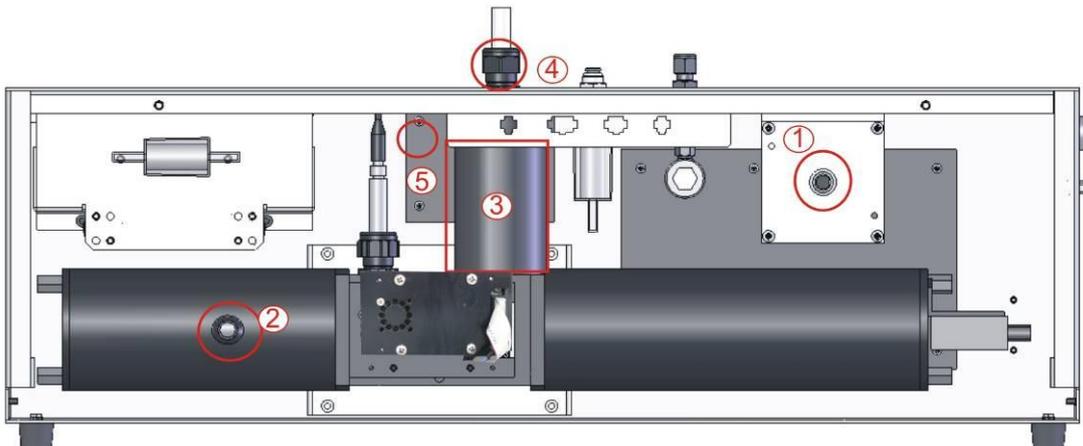


Figure 44 Internal pneumatic tubing

6.3.9 PMT Replacement

This procedure is for replacing the Photo Multiplier Tube (PMT) in the Aurora. This is not part of the routine maintenance and should only be performed on the advice of Ecotech engineers. It should only be performed by qualified Ecotech personnel or suitably trained field technicians. Please read through this procedure first before commencing any work.

CAUTION! This procedure involves handling light sensitive equipment. Make sure that all power is off at all times. Exposing the PMT to light when it is on will cause irreversible damage to the PMT. Exposure to strong ambient light can also cause short term instability. Be sure to keep the PMT covered at all times.

Removing PMT

1. Follow the steps 1 to 16 from section 0 for removal of the optical chamber.
2. Now the PMT should be fully exposed.
3. The PMT is mounted on a bracket which is connected to the chamber end-plate with two M4 screws. Before removing this bracket, make sure you have ready a black bag or cloth to put the PMT in. Also, between the PMT and the cell end plate there is a small V-Ring o-ring which will fall out when the PMT is removed. Do not lose this o-ring.
4. Remove the PMT, O-ring and bracket and place in the black bag.
5. Now remove the PMT bracket from the PMT by unscrewing the 4 M3 screws. Each screw should have a spring washer, flat washer & white insulator. Please do not lose these.



Figure 45 Removing the PMT

6. Before removing the PMT completely, note the orientation of the PMT in relation to the optical chamber and bracket.

Installing new PMT

7. Now take the new PMT from its box. Remove its protective black cover from its window and place it on the OLD PMT.



Figure 46 New PMT inserted

8. Then screw the new PMT onto the PMT bracket with the 4 M3 screws.
9. Attach the PMT bracket to the cell end plate and make sure the V-ring is re-inserted flat and its sides are not twisted.
10. Re connect the 2 cables and push the black tubing in firmly.
11. Replace the black rubber cap making sure there are no gaps around the optical chamber.
12. Return the assembled optical chamber to the instrument in the reverse order to which it was removed.
13. Double check all connections before turning the instrument on.

Restarting the instrument:

14. After turning on the power, observe the dark count. It should be stable and typically less than 1000. check for further light leaks by turning off the room lighting and looking for a decrease in dark count.
15. In the system counts menu, check that the shutter counts and measure counts are all within their limits. (shutter count 0.8M to 1.6M, measure count greater than 10K)
16. When you are confident that everything is good, perform a leak check, then close the front panel.
17. Allow the Aurora to warm up for at least 10 minutes, and then perform a Full Calibration.
18. After the calibration, verify that the ambient readings are realistic and stable.
19. Return the faulty PMT to Ecotech.

6.3.10 Optical Chamber Cleaning

In order to clean all parts of the optical chamber, then optical chamber should be completely removed from the instrument. Refer to Figure 44 above. This procedure should include the step for cleaning the Measurement cell as in section 6.3.2.

Optical Chamber Removal:

1. Follow the steps (1 to 5) from section 6.3.2 to remove the light source
2. Remove the lower part of the inlet heater insulation by undoing the black Velcro strap (3).
3. Using the adjustable wrench disconnect the sample inlet heater from the cell by turning the brass feral anti-clockwise. Use a second wrench to hold the bottom fitting.
4. Loosen the black cable gland (4) at the top of the inlet and pull it up so that it is clear of the measurement cell.
5. Disconnect the sample temperature sensor by turning the outer metal sleeve anti-clockwise and pull up.
6. Disconnect the two heater cables (5) on the power control board.
7. Disconnect the reference shutter cable from the panel connector labelled "Shutter".
8. Using a long flat screwdriver, unscrew the 4 captive screws at the base of the measurement cell mounting plate.
9. Remove the large black tube off the optical chamber exhaust port (2).
10. Disconnect the small black tube on the left hand end of the chamber.
11. With almost everything disconnected, carefully pull the optical chamber out and rest it on the front door with some bubble wrap under it to protect it.
12. Carefully pull back the large black rubber cap on the right hand end of the chamber. There are 2 cables and 1 small black tube penetrating this cap.

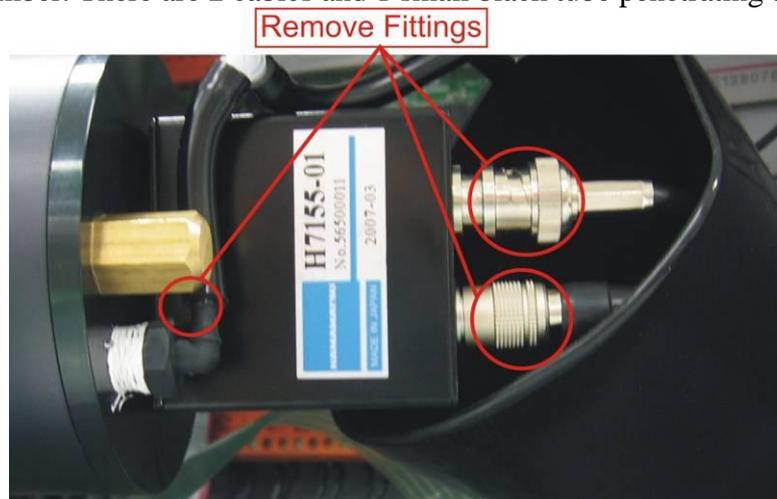


Figure 47 Removal of cell fittings

13. Remove the black tubing from the port.
14. Disconnect the coaxial cable by rotating it anti-clockwise and pull.
15. Remove the other smaller cable by pulling back the outer metal ring, then pull.
16. Now the optical chamber should be completely free to move.

Cleaning Reference Shutter:

17. Remove the 2 brass nuts at the PMT end of the chamber and do not lose the 2 small o-rings.
18. Remove the chamber end plate and PMT assembly by pulling it out. A small amount of wriggling will be required because of the o-ring seal. Cover the PMT to ensure that the PMT's exposure to light is minimised
19. Remove the chamber cylinder on the right side (PMT side) by carefully pulling it off. Try to avoid scratching the cylinder's walls.
20. Clean the reference shutter glass with a lint free tissue or cotton bud and warm clean water, then leave to dry. If the baffles are dirty, clean them in a similar manner or by using compressed air.
21. Check that the reference shutter adjustment screw in the side of the shutter plate is not loose.
22. Check the O-rings for cracks or dirt and clean if necessary. Avoid using O-Ring grease.

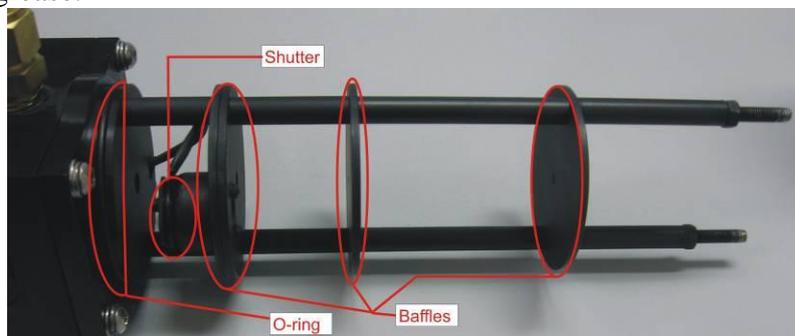


Figure 48 Optical chamber right cylinder components

Cleaning Light Trap Mirror:

23. Remove the 2 brass nuts at the left hand end of the chamber and do not lose the 2 small o-rings.
24. Remove the chamber end plate from the left end of the optical chamber cylinder (light trap) by pulling it away from centre. A small amount of wriggling will be required because of the o-ring seal.
25. Be very careful not to touch the mirror surface.
26. Slide the outer cylinder off making sure not to scratch the inside surface.



Figure 49 Removing Light Trap

27. Inspect the light trap mirror surface using a very bright torch (eg LED type), and viewing it from various angles. Look for signs of white streaks or dust in the centre of the glass.
28. If the glass surface does need cleaning, use a precision electronic cleaning solvent which leaves no residue, low toxicity and has a CO₂ propellant (CRC CO Contact Cleaner). **DO NOT USE Isopropanol (IPA).**

29. Spray the electronic cleaning solvent on the surface of the glass, then quickly using a lint free tissue, remove the solvent in one continuous sweep covering the full width of the glass. Then re-inspect with a torch for no residue.
30. Surface dust can be cleaned by lightly blowing or using a horse hair camera lens cleaner.
31. If the baffles are dirty, clean them with a lint free tissue or cotton bud and warm clean water or by using compressed air, then leave to dry.
32. Check the O-rings for cracks or dirt and clean if necessary. Avoid using O-Ring grease.

Optical Chamber replacement:

33. With all parts of the chamber cleaned and dry, it is now time to replace the chamber back to its original position.
34. Slide the two cylinders back on the push the light trap end plate and PMT end plates on.
35. Tighten the 4 brass nuts and o-rings on each end to seal the optical chamber.
36. Now replace the optical chamber into instrument and replace all connectors and pneumatic connections in reverse order to steps 1 to 16.
37. With everything connected, perform a leak check, then a full calibration before normal operations can begin.

6.3.11 Zero Noise Test

Calculating the zero noise is the best way to confirm the operational performance of the Aurora 4000 Nephelometer. The following procedure explains how to do this:

1. Operate the Aurora 4000 at room temperature for at least 30 minutes before starting the test.
2. Set the Aurora 4000 into zero calibration mode for a period of 2 hours. This can be done by using either of the following three methods:
 - In the calibration menu, set the minimum calibration time to 120 minutes, and the maximum calibration time to 121 minutes, then set it to do a zero check. Or
 - On the 25pin external IO connector, connect pin 7 (DO ZERO) to pin 20 (Digital GND) to put it in zero mode. or
 - Connect an external Disposable Filter Unit (DFU) to the sample inlet during normal sampling mode, or
 - In hidden menu 2, from the counts menu, set Span/Zero Ovr to 032 (016 will put it into span measure and 000 is normal sample measure)
3. In the Data Logging menu, set the Log Period to 1. minute.
4. Clear the Data Log memory. (be sure you have downloaded any previously logged data that you may need).
5. Allow the Aurora 4000 to continue running on zero air for a period of 120 minutes (2 hours), uninterrupted.
6. When the 2 hours are complete, connect the Aurora 4000 to a PC using the RS232 cable and use the installed Aurora Data Downloader software to download the 2 hours of zero data to the PC.
7. Using MS Excel, import the data into a new spread sheet.
8. For the scattering data use the STDEV() command in Excel to calculate the Standard Deviation of the zero data over the 2 hour period for each of the 6 scattering parameters.
9. This calculated standard deviation is the zero noise value for that particular instrument.
10. If the zero noise is less than **0.15Mm⁻¹**, then the instrument is considered to be in good working order.

If the instrument zero noise is above 0.15Mm⁻¹, then this could be due to a number of factors:

- Pneumatic leak in the cell or plumbing,
- Light leak near the PMT,
- Dirty measurement cell or optical chamber,
- Low intensity light source,
- Dirty light trap mirror,
- Noisy PMT

6.3.12 Light Source Check

The performance of the light source and backscatter shutter can be verified without having to remove the light source from the measurement cell. The following procedures are simple checks which can be done. Ultimately the, calculating the zero noise is the best way to confirm the overall operational performance of the Aurora 4000 Nephelometer. See section 0.

Performance Verification:

1. Visually inspect the operation of the light source by looking down the sample inlet tube. You will see a sequence of **Red, Green** and **Blue** flashes inside the cell.
2. Enter the first hidden menu by pressing the hidden key which is located directly below the “exit” key on the keypad. Select the “**Light Source** menu”.
3. Verify that the parameters in the **Light Source** menu are as follows:

Manual Mode	NO
Wavelength 1	635nm
Output 1	NO
ST CorConst1	0.6000*
LED 1	100-250*
Wavelength 2	525nm
Output 2	NO
ST CorConst2	0.5000*
LED 2	100-250*
Wavelength 3	450nm
Output 3	NO
ST CorConst3	0.0000*
LED 3	100-250*
Set LED Pots	→
Backscatter	YES
Cal BackScat	160 to 180*
ManualBackOn	NO

These parameters should match those given on the instrument test sheet supplied with the Aurora 4000.

Note: that these settings may be different for each instrument.

4. After the Aurora 4000 has been running for 2-3 minutes, enter into the **Sys Status** menu from the Main Menu, and verify that all parameters **PASS**.
5. Enter into the **Sys Counts** menu from the Main Menu and verify that the Dark Count is less than 1000 and relatively stable. (Note the dark count can go above 1000 if the cell temperature is higher than 30°C.
6. Enter the **Wavelength 1** menu. The readings will vary, but may be similar to the following:

Shtr Count 1	1.085M*
Meas Count 1	14.55k*
Meas Ratio 1	14.21m
BS Meas Cnt1	12.30k*
BS Meas Rt 1	11.79m

7. Verify that the **Shutter count** is between **0.800M and 1.6M**.
8. Verify that the **Measure count** is greater than **10K**.
9. Verify that the **BS Measure count** (Backscatter) is **less than the Measure count**.
10. Repeat steps 7 to 9 for **Wavelength 2** and **Wavelength 3** menus.

Note: It is recommended that these values be recorded in a system log for book for future reference and should be quoted if contacting Ecotech for assistance.

11. Open the front panel and verify that the **Fan** on the back of the Light Source control board is running.
12. Verify that the Green LED on the Servo Controller (black box) is ON. The Red LED may flash at startup, but wait until the Instrument warm up period has completed, then check that the **Green LED** is on.

Light Source Adjustments:

If the Shutter counts or the Measure counts are too low or too high, they can be adjusted in the **Light Source** Menu mentioned above.

1. To increase the shutter count or Measure count of Wavelength 1, increase LED1 up to a higher value, but no higher than a maximum of 250.
2. Return to the **Sys Counts** menu and check that the Shutter and Measure counts for wavelength 1 are at an acceptable level.
 - a. Note that the shutter count is only updated every 30 seconds.
 - b. The shutter count and measure count will increase or decrease proportionally when adjusting the LED1 setting.
 - c. The backscatter measure count should be at least 1K or 2K less than the measure count.
3. Now repeat the same procedure for wavelength 2 by adjusting LED 2 and verifying its Shutter and Measure counts.
4. Now repeat the same procedure for wavelength 3 by adjusting LED 3 and verifying its Shutter and Measure counts.

For each wavelength, the optimum settings are for: Measure count > 10K, Shutter count ~1.2M (0.8M minimum and 1.6M maximum.

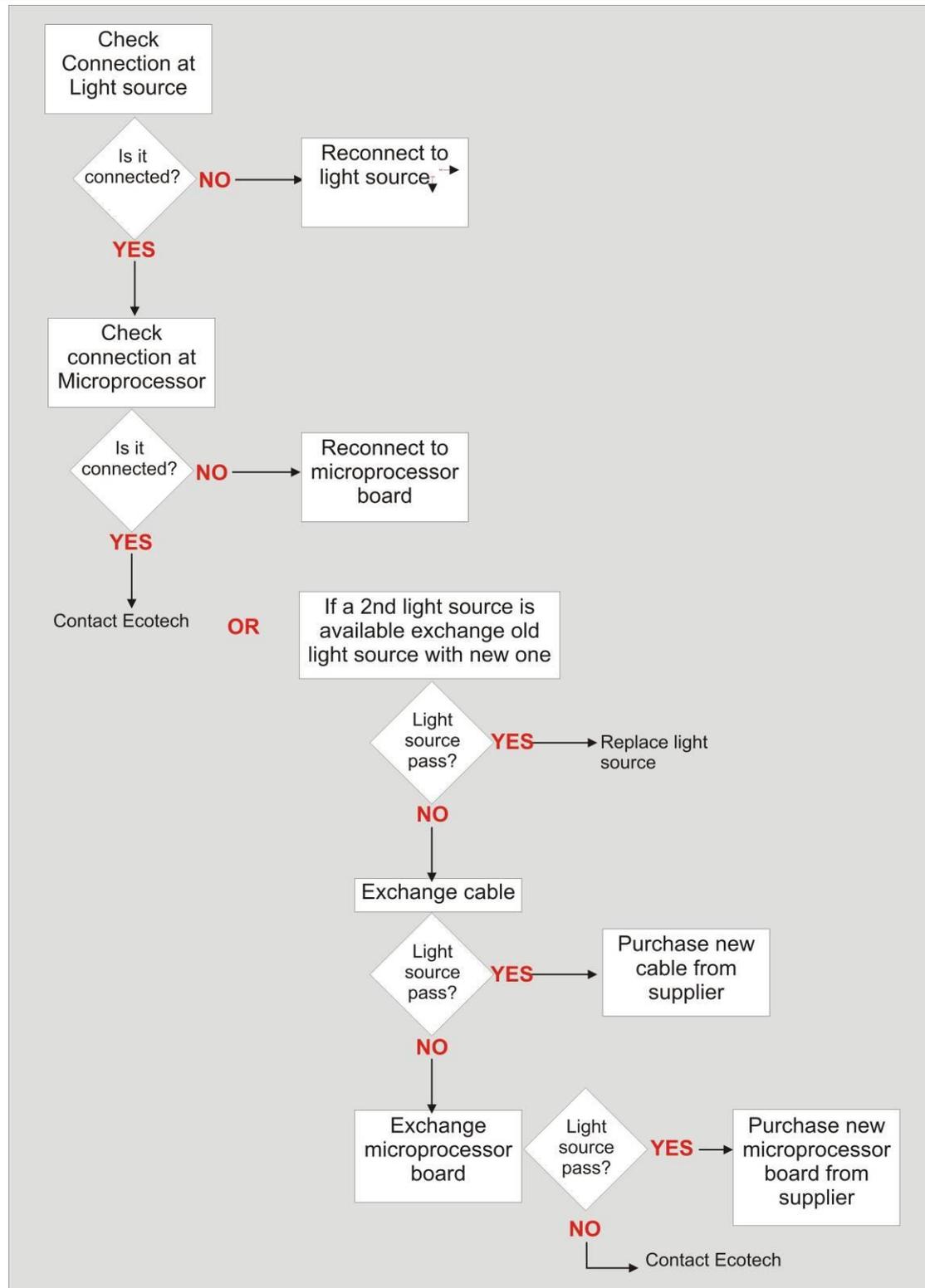
LED 1,2 & 3 should be between 100 and 250.

If you cannot adjust the shutter count above 0.8M, then please contact Ecotech for further instructions on how it can be adjusted.

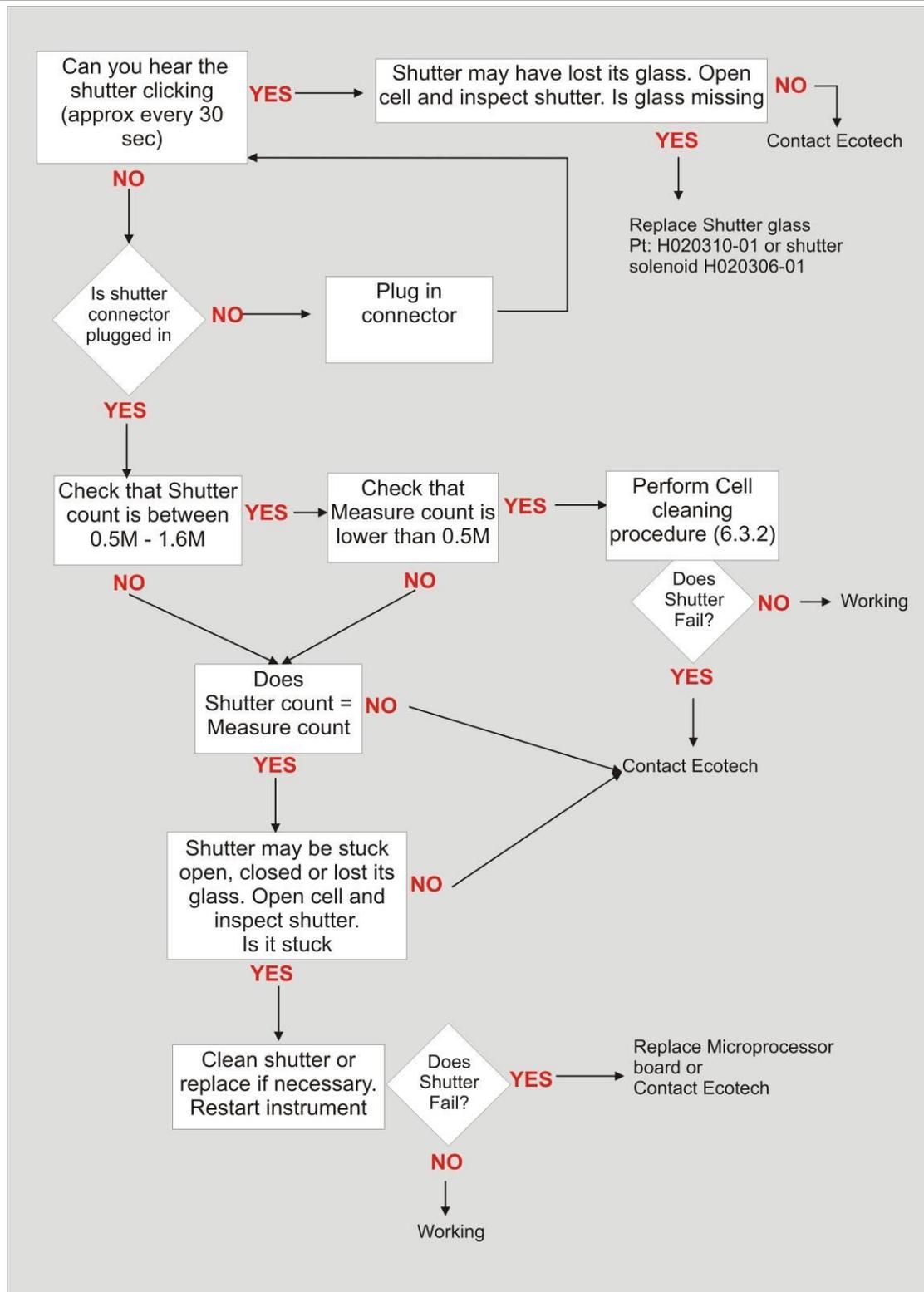
5. If the light source parameters have been adjusted, then a full calibration will be required.

7 Troubleshooting

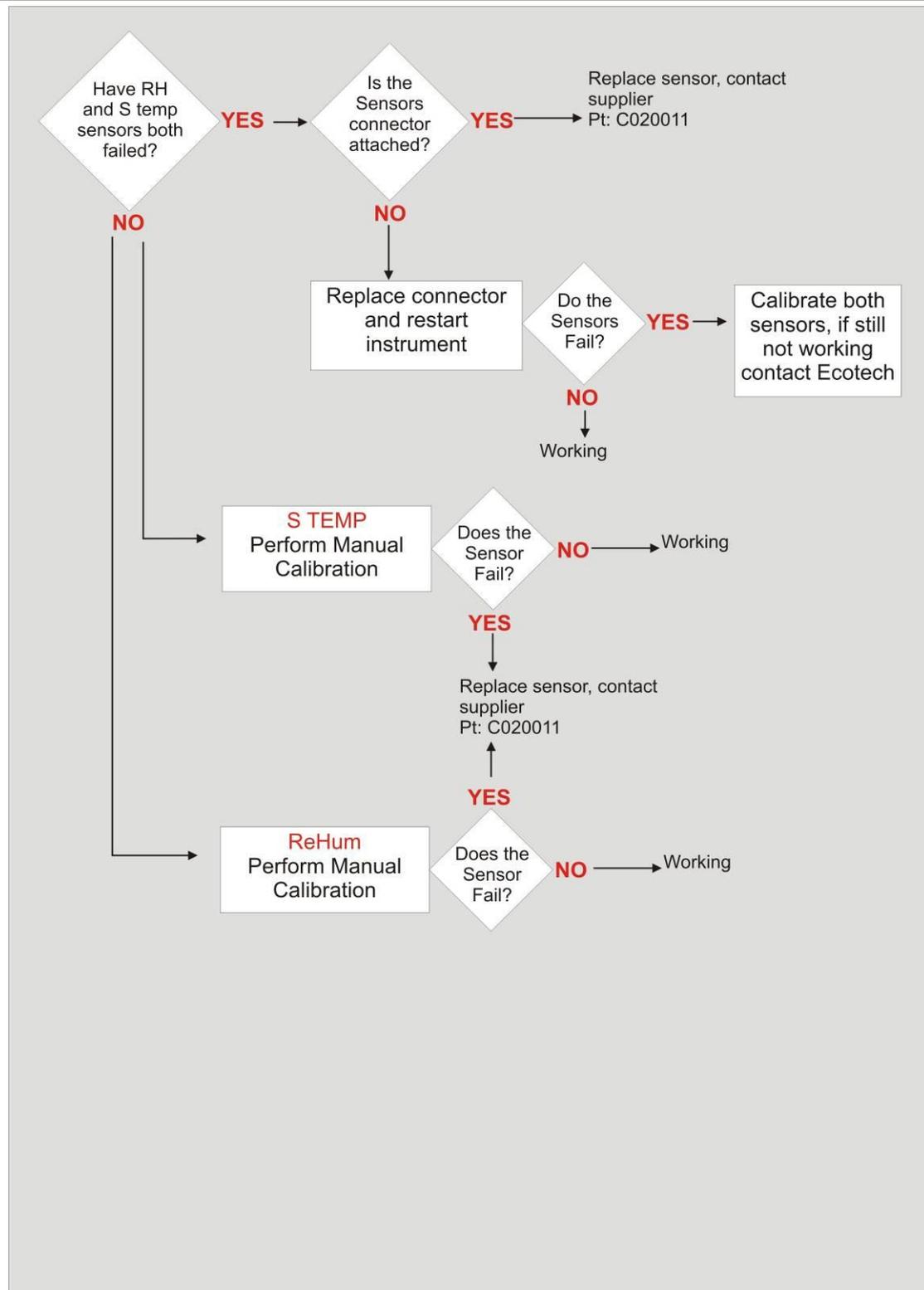
7.1 Lightsource Fail



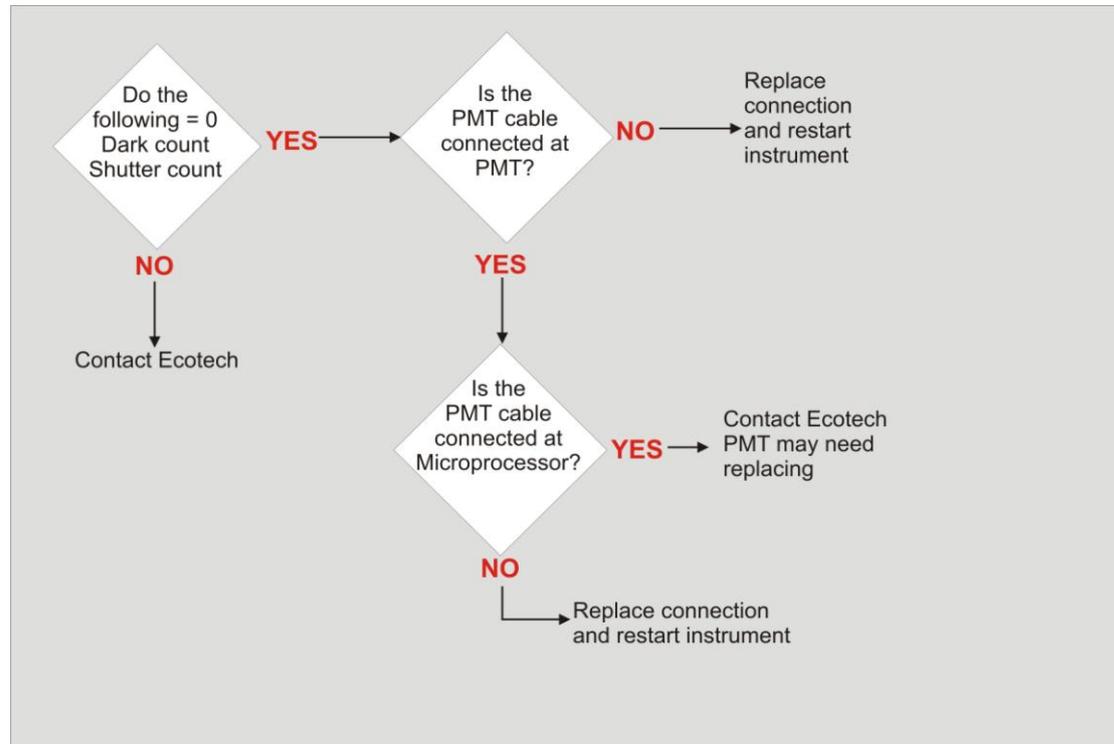
7.2 Reference Shutter Fail



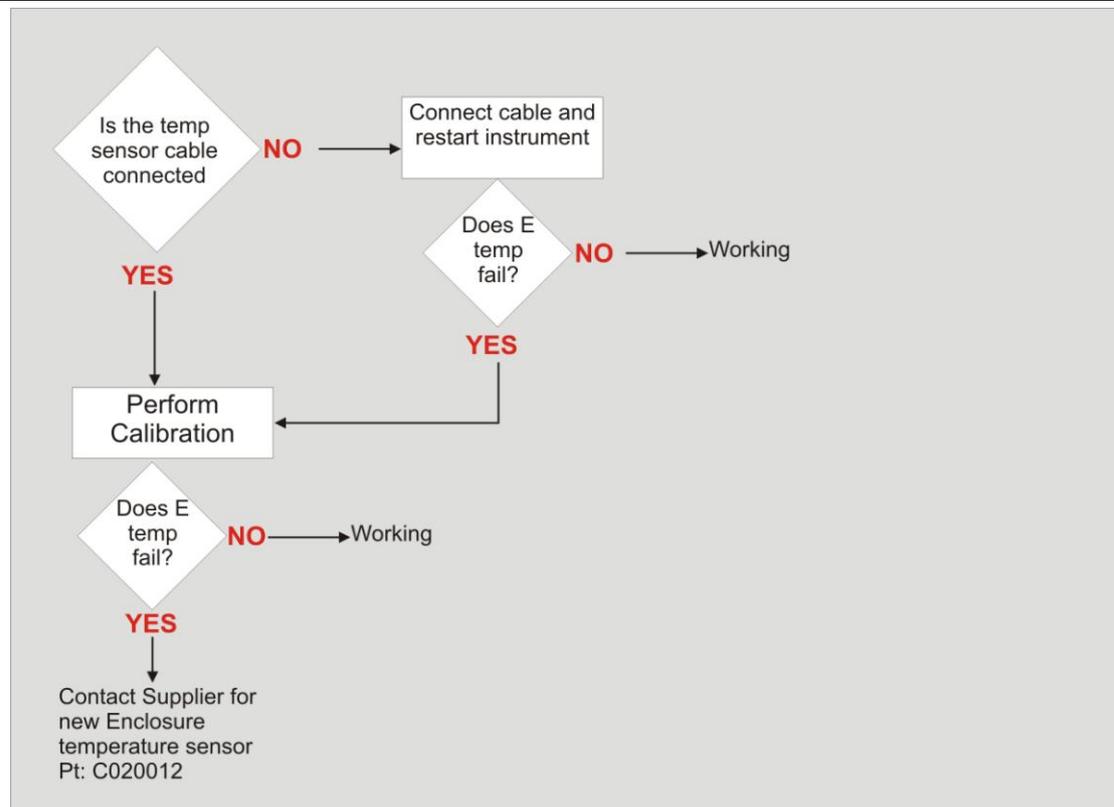
7.3 RH sensor & Temperature sensor fail



7.4 PMT Fail



7.5 Enclosure Temperature sensor Fail



Appendix A Aurora Command Set

Command: ID

Polls the Aurora 4000 for the instrument type, the current software/firmware version and the unique factory allocated identification number of the Nephelometer.

Syntax: ID{<module address>}<cr>

Response: Ecotech Aurora 4000 Nephelometer v{<firmware version number>}, ID #{<instrument ID number>}<CR><LF>

Example: ID0<CR> may respond with:
Ecotech Aurora 4000 Nephelometer v2.00, ID #123456
<CR><LF>

Related Commands: Pressing CONTROL-T also gives the same response.

Command: ^T

Instructs the Aurora 4000 to listen for *** commands (B, D, and R).

Syntax: ^T<CR>

Response: Ecotech Aurora 4000 Nephelometer v1.16.000, ID #nnnnnn<CR><LF>

Command: ***B

Erases the data log memory.

Syntax: ***B<CR>

Response: OK<CR><LF>

Command: ***D

Downloads the new content of the data log. The number of responses will depend on how many entries are in the data log that have not yet been downloaded.

Syntax: ***D<CR>

Response: Multiple comma separated data entry: Time, Status, Type, scattering values for each wavelength & angle, air temp, cell temp, humidity, and pressure <CR><LF>

Command: ***R

Rewinds to the beginning of the data log. The next ***D command will download the entire contents of the data log.

Syntax: ***R<CR>

Response: OK<CR><LF>

Command: **PS

Programs the unique factory allocated identification number of the Nephelometer into memory. This number can be found in the bottom line of the main menu.

Syntax: **{<module address>}PS{space}{<instrument ID number>}<CR>

Response: OK<CR><LF>

Arguments: <instrument ID> is a six digit number allocated by Ecotech to each individual instrument.

Example: **0PS_123456<CR> responds with: OK<CR><LF> and sets the instrument ID number to 123456.

Command: **B

Re-Boot test. When initiated the Watchdog timer will be activated and cause the Aurora 4000 microprocessor to re-boot. The same as pressing the reset button on the microprocessor board.

Syntax: **{<module address>}B<CR>

Response: null

Example: **0B<CR> will re-boot the Aurora .

Command: **M

Enables / Disables the remote menu feature of the Aurora 4000. When enabled, the user can perform all menu operations remotely using a RS232 terminal connected to the Service port.

Syntax: **{<module address>}M{<remote menu status>}<CR>

Response: OK<CR><LF>

Arguments: <remote menu status> = 1 turns the remote menu ON.

 <remote menu status> = 0 turns the remote menu OFF

Example: **0M1<CR> responds with: OK<CR><LF> and turns the remote menu on.

Command: **S

Sets the real-time clock on the Aurora 4000 microprocessor board. A single command can set the time and date.

Syntax: **{<module address>}S{<hhmmssddMMyy>}<CR>

Response: OK<CR><LF>

Arguments: <hhmmssddMMyy> is the current time and date. (hh) hour, (mm) minutes, (ss) seconds, (dd) day, (MM) Month, (yy) year.

Example: **0S142536061003<CR> responds with: OK<CR><LF> and sets the clock to: 14:25:36 on 6/10/2003.

Command: **PC

Programs the calibration parameters for the analog inputs and analog outputs. This is used mostly during factory calibration.

Syntax: **{<module address>}PC{<calibration parameter>}{<calibration value>}<CR>

Response: OK<CR><LF>

Arguments: <calibration parameter> = one of the following:

- 0 Calibration Pressure X point - pressure in kpa at calibration point.
- 1 Calibration Pressure Y point - A2D reading at calibration point.
- 2 Calibration thermistor factor - A2D reading of thermistor at 25 degrees.
- 3 Calibration Vaisala temperature offset - Vaisala temperature offset at minimum reading.
- 4 Calibration RH gradient - Vaisala RH gradient correction factor.
- 5 Calibration RH offset - Vaisala RH offset adjustment.
- 6 Analogue Output Current 1 Zero A/D point.
- 7 Analogue Output Current 1 Full A/D point.
- 8 Analogue Output Current 2 Zero A/D point.
- 9 Analogue Output Current 2 Full A/D point.

<calibration value> = an appropriate value to set each calibration point.

Example: **0PC01013.25<CR> responds with: OK<CR><LF> and programs the calibration pressure X point to 1013.25.

Command: **J

Forces or Jumps the Aurora program into one of the 8 major states. This is used mostly during factory testing.

Syntax: **{<module address>}J{<major state number>}<CR>

Response: OK<CR><LF>

Arguments: <major state number> = one of the following:

- 0 Normal Monitoring.
- 1 Span calibration (adjusts calibration curve).
- 2 Zero calibration (adjusts calibration curve).
- 3 Span check.
- 4 Zero check.
- 5 Zero offset adjust (adjusts calibration curve).
- 6 System calibration / startup.
- 7 Environmental calibration.

Example: **0J6<CR> responds with: OK<CR><LF> and forces the Aurora 4000 into system calibration (or start up).

Command: DO

Overrides the digital input & output control. Most commonly this command is used to force the Aurora 4000 into either span or zero measure mode.

Syntax: DO{<module address>}{<digital parameter number>}{<digital parameter state>}<CR>

Response: OK<CR><LF>

Arguments: <digital parameter number> = one of the following:

- 00 External DOSPAN control override.
- 01 External DOZERO control override.
- 02 Filtered air valve on/off (not used).
- 03 Output valve on/off (not used).
- 04 Digital out Aux control override.
- 05 Sample pump control override.
- 10 LCD backlight control override.

<digital parameter state> = 1 turns digital parameter ON.

<digital parameter state> = 0 turns digital parameter OFF.

Example: DO0001<CR> responds with: OK<CR><LF> and sets the Aurora 4000 into span measure.

Command: VI

Reads up to 100 different parameters from the Aurora 4000 microprocessor. Ideal for data logging devices which can poll the instrument for its data.

Syntax: VI{<module address>}{<voltage input parameter number>}<CR>

Response: {<sign>}{<parameter value>}<CR><LF>

Arguments: <sign> = <space> if positive, <-> if negative. (if the output is an ASCII character, then there is no <sign>).

<parameter value>= a value which can be either an ASCII character string, or a decimal number to six decimal places.

< voltage input parameter number > = one of the following:

Note: See extensions for polar nephelometer VI commands after the table below

Aurora 4000 Backscatter	
00	Current Monitoring State (Major.Minor) 2 decimal places for minor.
01*	Scat coefficient Channel 1. Mm ⁻¹ (RED)
02	Scat coefficient Channel 2. Mm ⁻¹ (GREEN)
03	Scat coefficient Channel 3. Mm ⁻¹ (BLUE)
04	Dark count (moving average).
05	Dark count last reading.
06	Shutter count Channel 1 (moving average).
07	Measurement count Channel 1 (moving average).
08	Measurement Ratio Channel 1 (moving average).
09	Shutter count Channel 2 (moving average).
10	Measurement count Channel 2 (moving average).
11	Measurement Ratio Channel 2 (moving average).
12	Shutter count Channel 3 (moving average).
13	Measurement count Channel 3 (moving average).
14	Measurement Ratio Channel 3 (moving average).
15	Sample Heater on time.
16	Relative humidity. %
17	Air temperature in current reporting preference.
18	Cell temperature in current reporting preference.
19*	Atmospheric pressure in current reporting reference.
20	Led pot 1 setting
21	Led pot 2 setting
22	Led pot 3 setting
23	

Aurora 4000 Backscatter	
24	
25	
26	Wavelength channel 1
27	Wavelength channel 2
28	Wavelength channel 3
29	
30	Backscatter Channel 1. Mm^{-1} (RED)
30	Backscatter Channel 2. Mm^{-1} (GREEN)
32	Backscatter Channel 3. Mm^{-1} (BLUE)
33	Backscatter Measurement count Channel 1 (moving average).
34	Backscatter Measurement Ratio Channel 1 (moving average).
35	Backscatter Measurement count Channel 2 (moving average).
36	Backscatter Measurement Ratio Channel 2 (moving average).
37	Backscatter Measurement count Channel 3 (moving average).
38	Backscatter Measurement Ratio Channel 3 (moving average).
39	
40	
41	
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Aurora 4000 Backscatter	
61	Desired RH setting (string).
62	Normalise temperature setting (string).
63	Span gas setting (string).
64	Date format setting (string).
65	Temperature unit setting (string).
66	Atmospheric pressure unit setting (string).
67	Zero check frequency setting (string).
68	Major state (string).
69	Minor state (string).
70	LED Set position (string).
71	RS232 DO span/zero measure mode status. 016= span, 032= zero.
72	St correction constant 1
73	St correction constant 2
74	St correction constant 3
75	St correction constant 4
76	St correction constant 5
77	St correction constant 6
78	Backscatter on position
79	
80*	Clock date (in current report preference format) (string).
81*	Clock time in hh:mm:ss format (string).
82	
83	
84	
85	
86	
87	
88	
89	
90	Digital output status – PortD (string).
91	
92	
93	
94	
95	
96	
97	

Aurora 4000 Backscatter	
98	The angle list the number of angles, followed by each angle degree as one comma delimited string.
99	Real time parameters obtained as one comma delimited string.

VI extension commands for the polar nephelometer

Syntax: VI{<module address> + 1, 2, or 3}{<angle value>}<CR>

Response: {<sign>}{<parameter value>}<CR><LF>

Arguments: <module address> +1, 2, or 3 = the module address of the Aurora 4000 incremented by 1, 2, or 3 to indicate the corresponding wavelength (first, second, or third).

<angle value> = a value between 0 and 90, inclusive. If that value is in the list of angles being measured, then the response is the scattering value for that angle and the indicated wavelength. If the value is not in the list of angles being measured, then -9999 is returned.

Example: If the module address is 0, then VI100 returns the scattering value for the first wavelength at angle 0. VI275 returns the scattering value for the second wavelength at angle 75 (or -9999 if that angle is not currently being measured).

<sign> = <space> if positive, <-> if negative. (if the output is an ASCII character, then there is no <sign>).

<parameter value>= a decimal number to three decimal places.

Note 1: Digital Output Status.

The VI090 command reads the Digital Output Status of the Aurora 4000 microprocessor board. The DIO status is the status of the digital outputs in hexadecimal. This enables you to determine exactly what the Aurora 4000 is doing. ie if in span or zero measure.

Syntax: VI{<module address>}90<CR>

Response: {<DIO state>}<CR><LF>

Arguments: <DIO state> = a hexadecimal number represented by the following:

- 00 Cell heater OFF
- 01 Inlet heater OFF
- 02 Sample pump ON
- 03 Zero pump ON
- 04 Span gas valve open
- 05 not used
- 06 not used

07 Digital aux out ON

Example: VI090<CR> responds with 07<CR><LF>.
Indicating: cell heater off, inlet heater off, sample pump on.
 VI090<CR> responds with 0B<CR><LF>.
Indicating: cell heater off, inlet heater off, sample pump off, zero pump on. (zero measure).
 VI090<CR> responds with 13<CR><LF>.
Indicating: cell heater off, inlet heater off, sample pump off, zero pump off, span valve open. (span measure).

Note 2: Single line output.

The VI099 command provides a unique output string. In one line it provides the time and date, scattering coefficient as well as the other meteorological parameters and current state information. The data is comma delimited.

Syntax: VI{<module address>}99<CR>

Response: {<date>},{<time>},{< σ_{sp} 1>},{< σ_{sp} 2>},{< σ_{sp} 3>},{< σ_{bsp} 1>},{< σ_{bsp} 2>},{< σ_{bsp} 3>},{<sample temp>},{<enclosure temp>},{<RH>},{<pressure>},{<major state>},{<DIO state>}<CR><LF>

Arguments: <date> = Current date. Format as set in Report Preferences.
 <time> = Current time. hh:mm:ss.
 <scattering> = Current σ_{sp} in Mm^{-1} .
 <air temp> = Current Air temp. Units as set in Report Preferences.
 <cell temp> = Cell temp. Units as set in Report Preferences.
 <RH> = Current Relative Humidity. Units in %.
 <pressure> = Current Barometric Pressure. Units as set in Report Preferences.
 <major state> = Major State as listed in Note 1. 2 digit number.
 <DIO state> = DIO State as listed in Note 2.
 <sign> = <space> if positive, <-> if negative.

Example: VI099<CR> responds with: 21/11/2010 09:45:27, 6.981, 8.723, 12.035, 2.254, 2.859, 3.012, 22.108, 21.710, 41.370, 1000.436, 00, 07<CR><LF>.
Indicating that it is in Normal Monitoring state.

VI099<CR> responds with: 21/11/2010 09:56:10, 6.981,
8.723, 12.035, 2.254, 2.859, 3.012, 22.894, 20.952,
40.671, 1000.642,04,0B<CR><LF>.
Indicating that it is in Zero Check state.

